



CABLE AND PIPE LOCATOR "SUCCESS AG-319G"

TECHNICAL DESCRIPTION OPERATING INSTRUCTIONS



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Introduction

- Detection of cables and any metal pipelines underground up to 10 m;
- Direct digital measurement of the depth up to 10 m;
- Indication of the deviation from the utility axis in the mode "ROUTE";
- Direct digital measurement of the current;
- Survey the ground before the excavation works;
- Distance of tracing from the place of transmitter connection is up to 5 km.

Intended use

- -Power
- -Public utilities
- -Oil and gas industry
- -Geodesy
- -Communication
- -Construction
- -Other industries

Operation conditions

-Ambient temperature, °C	from -20C to +60
-Relative humidity, %	up to 85 at t=35 °C
-Pressure, kPa,	84 to 106
-Device protection class	IP 54

Receiver working principle

«Success AG-319G with integrated GPS/Glonass is used to locate cables and pipelines underground».

GPS/Glonass and usage logging allow to generate the data and transfer it to the PC via USB cable and special software program (V1.09 Beta User Manual). 2000 points can be stored.

The Cable and pipe locator «Succes AG-319G» consists of the electromagnetic radiation receiver and transmitter providing for the electromagnetic radiation of the route being detected.

According to the signal of the embedded speaker or headphones and using the graphic display indications the operator determines the route location.

The receiver is capable of receiving a signal from industrial frequency radiation sources (50/60 Hz) and cathode protection systems (100/120 Hz). These modes are used for detecting the location of cable runs or routes carrying the voltage of the relevant frequency.

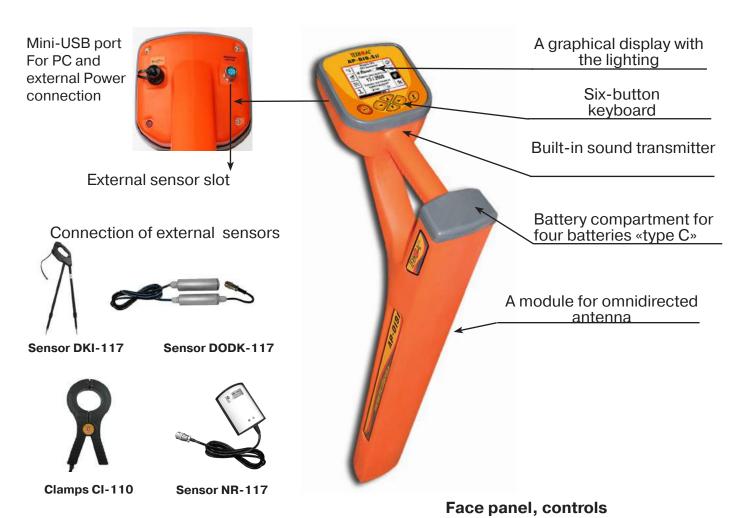
Cable or pipeline may be the load for generator. The transmitter can be connected to the load either directly (with connecting wires) or with the use of the inductive antenna or inductive clamp providing for contactless (inductive) connection of the utility under examination.

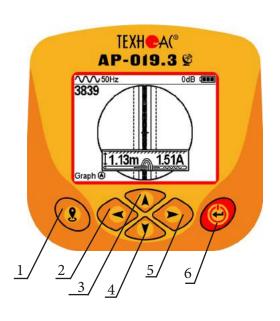
Use of the inductive antenna as a load is only possible at the 8,928 Hz frequency (selected automatically at antenna connection).



1. Appearance, AP-019.3 receiver controls

AP-019.3 receiver is made in the solid cast IP54 body to the battery compartment the body provides the protection IP68, the device can be splitted in three components: the face panel with controls and displays, battery compartment and bottom part with the antenna block. On the back side of the face panel, there are two slots for external connections (sensors and PC).





«Power»/«Enter» button (6) Switching on/off the receiver (to turn off the receiver, press and hold this button for 2 seconds) - open menu, - enter into the editing mode of the selected menu option, - exit for the editing mode saving selected parameters. Buttons «Up» (3), «Down» (4), «Right» (5), «Left» (2). - selection of the menu option (icon), - selection or changing the parameter inside the menu. - fast setting of the parameters «GPS» button(1) -Save coordinates and other available parameters of the point



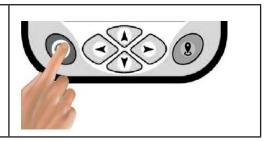
2. Receiver menu description

2.1 Receiver switching on and menu call

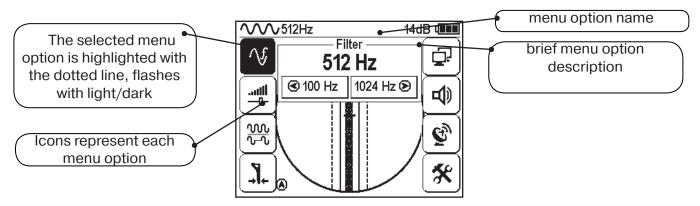




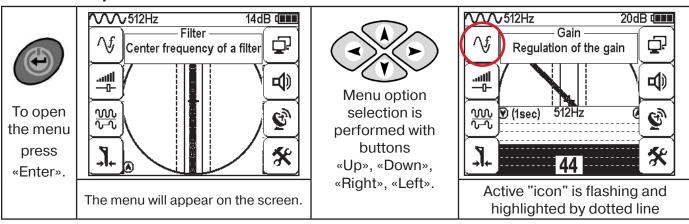
Press «Enter» button to open the Menu

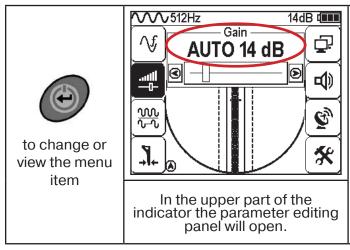


2.2 The general view of the menu screen



2.3 Menu parameter selection







Values setting is performed with buttons «Up», «Down», «Right», «Left».

The changed value is immediately applied.



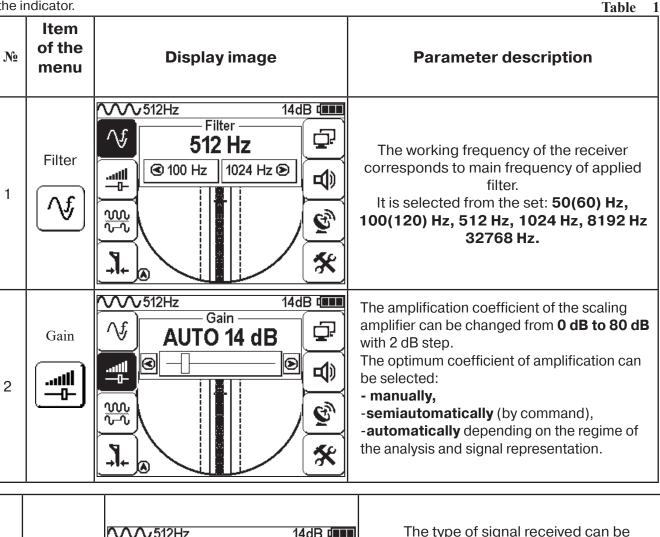
To exit into main menu or switch to the set mode with the closing of the menu, press «Enter». button If you wait for several seconds, menu will disappear automatically.

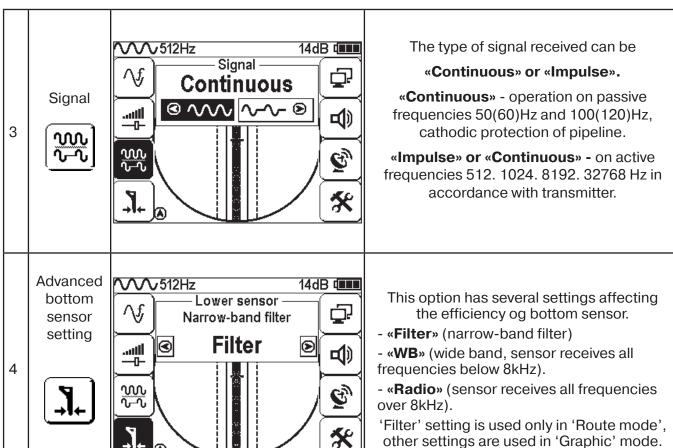
If you don't press any buttons for a period of time, the menu will disappear automatically. The length os this period is set in the corresponding menu option (see Table 1. p.6)



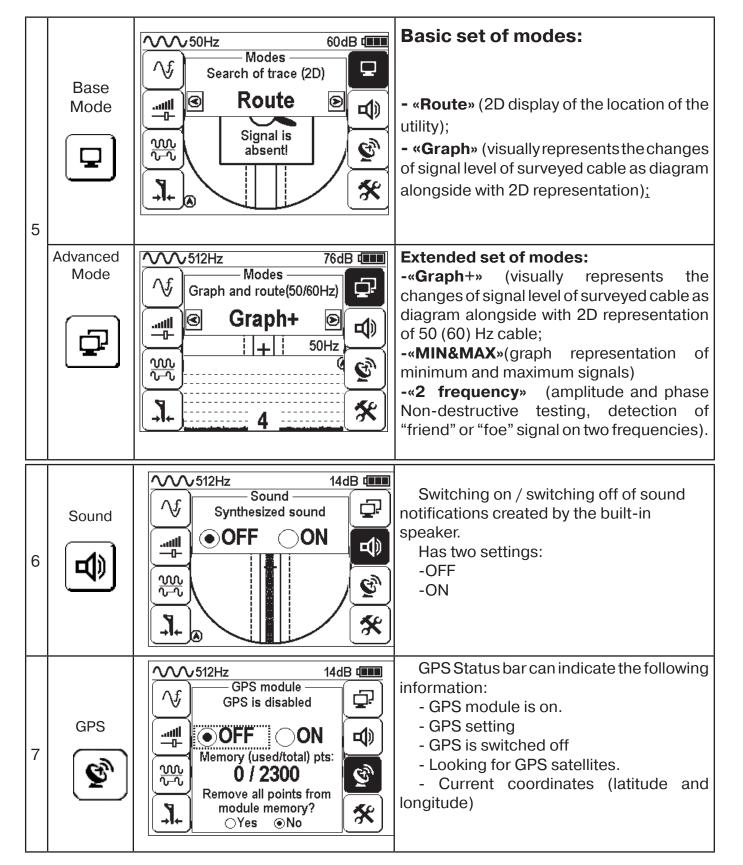
8 items of menu contain parameters of setting, which are opened in the panel located in the upper part of the indicator.

Table











3. Start of work

Before start of work, you should install the batteries into the corresponding compartment of the receiver in the following sequence:



Unsnap Battery compartment. Pull out the ring on the receiver handle



Install the batteries. observing the polarity



Install four new elements into the battery compartment of the device, minding polarity Install the battery compartment into the body until it snaps.

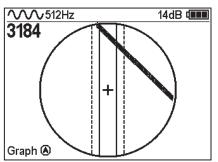
Receiver switching on

To switch on the receiver press the button «Power»

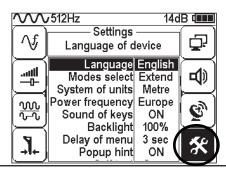
The screen saver will appear on the screen with the indication of the Firmware version, manufacturer and device name

The screensaver is followed by voltage and battery charge indicator...

Then the receiver will automatically enter into the mode «Route» in 5 seconds. At the first switching the factory settings are set by default. The filter frequency is 50 Hz.



The description of factory settings can be found in the menu «Parameters». You can go back to factory settings by selecting the parameter «reset settings»



With factory settings enabled you can perform the cable location with network frequency 50 Hz in without transmitter.



4. Search of cables in the mode «Route»

The Route mode is the main mode for route location of various communications (cables, pipelines) at all frequencies supported by the receiver, both a «passive» cable route location, and at the «active» (with the use of the route locating generator). In the passive mode the cable location is carried out at frequencies **50(60)100(120)Hz**, in the **active mode -512,1024, 8192, 32768 Hz**.

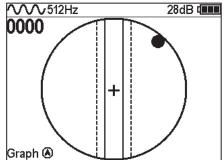
4.1. Cable location in the passive mode

This mode is used to search and locate a route of power cables under voltage with the frequency 50(60) Hz and other communications with the induced signal in frequency 50(60) Hz. The filter set on the receiver - 50(60) Hz. The external generator is not used.

4.2. Search of a communication and measurement of its burial depth.

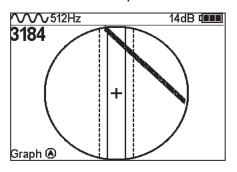
1. Come to the supposed place of the communication under the voltage or induced voltage in frequency 50(60) Hz.

2. If the communication is far from the operator, you will see on the screen:



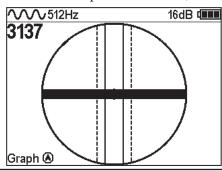


3. When moving towards the supposed place of the communication location, the «ball» will appear on the screen. It shows the presence of communication, and that it is on the significant distance from the operator.





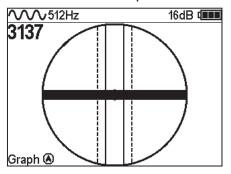
4. The «ball» position shows, in which direction from the operator the communication is located.







6. When operator moves closer to the communication, the axis will move to the circle center. This means that the operator is standing strictly over the communication.

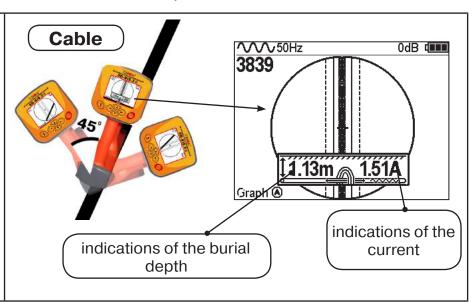




The measurement of the burial depth of communication

7. Further you should rotate the device, until the communication axis is aligned along the receiver axis. In this position and f the current in the cable is sufficient the window will appear displaying its burial depth and current. Now, the operator stands alongside the communication.

In this position, it is possible to move forward and trace whole cable.)

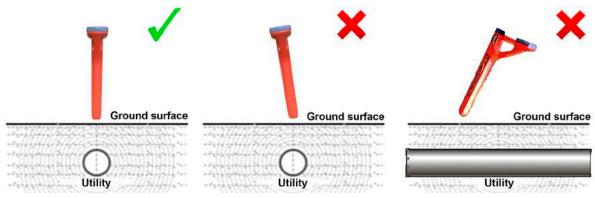


The power cables most frequently lay at the depth of 60-80 cm, allowing to differ them from pipelines. It is possible that cable lays in one channel with the pipeline, when the burial depth can be significantly exceed 1 meter.

If the communication axis cannot be located exactly in the limited area, and the periodical jumps are happening from the one border to the other, it tells about the presence of several cables under voltage with the 50 Hz frequency. You can specify number and position the cables in «Graphic» mode.

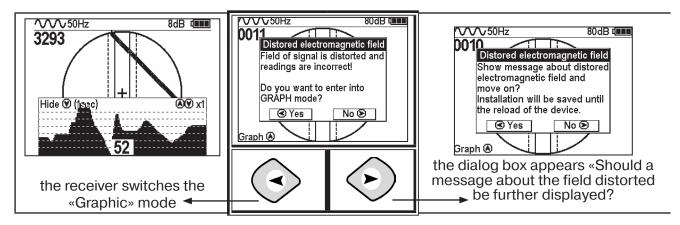
Attention:

Before measuring the depth of the utility, make sure that your device is positioned perpendicular to the utility. Even slight deviation from vertical position can influence the precision of depth measurement.

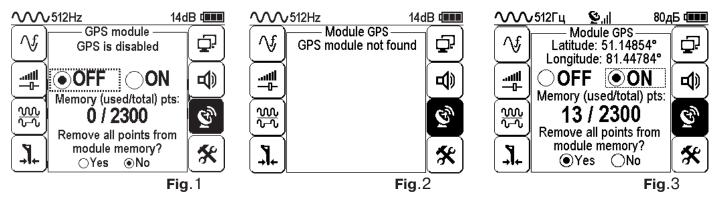




In the case when the signal is significantly distorted, the receiver automatically shows the notice about field distortion, offering switching the mode to 'Graph'



4.3. GPS Module in the receiver AP-019.3



GPS module is enabled from the main menu of the receiver.

When you open GPS menu entry happens the following:

- 1. The receiver issues module connection command (this procedure may last 0.5 sec.).
- 2. If response from the module is received, the receiver requests the number of available GPS points in module's memory and shows this information on the screen (see fig.1)
- 3. If the module doesn't respond, the receiver shows the message "GPS module not found" (see fig.2)

The display of the receiver has the following indication:

- 1) GPS module status:
- a. GPS off.
- b. Looking for GPS satellites.

Current GPS coordinates (longitude and latitude in degrees in 5 digits precision. See fig. 3).

- c. GPS module error.
- 2) GPS ON\OFF button.
- 3) GPS module memory status: shows the number of saved points in relation to available memory. YES\NO buttons for module memory clearance: If you select "Yes", you will see the confirm dialog window. Memory clearance is an irreversible action.

«POINT» - is a form of entry in device's or PC memory. It holds current operating frequency of the receiver, burial depth of the located utility(if available), current, going through the utility (if available), and also current longitude and latitude of the receiver position (if available) and also current date and time. (if available)

Saving of the point is performed by pressing GPS button on the receiver. If GPS module is active, it finds the necessary number of satellites and indicates coordinates in GPS menu. It means that the following data will be written in the memory: current coordinates, date and time. If receiver indicates burial depth and or current, floating through the utility, while saving of the point is enabled, you will have this data also saved in receiver's memory.



4.5. Cable route location in the active mode

This mode is used to locate the power cables under voltage (and without voltage) and other current-conductive communications, using the external generator. The route location is possible at frequencies **512**, **1024**, **8192**, **32768** Hz.

The filter on the receiver is set manually in accordance with the selected generator frequency.

When locating the cable route in the conditions of the large number of surrounding utilities you should set the frequency to 512 Hz.

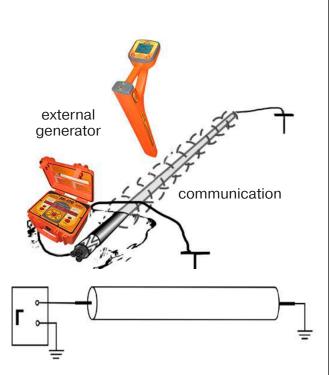
When it is impossible to ground the connection, you should select higher frequencies. To perform the cable location with damage detection, you should select the higher frequencies.

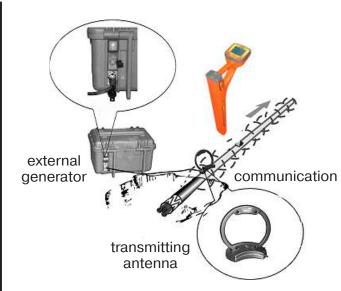
Transmitter Connection

Contact mode

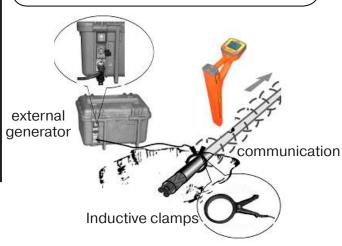
The generator output is connected directly to the communication

Contactless method using the transmitting antenna





Contactless method using the induction clamps



Jote

Note



Procedure for search of communication and conduction of cable route location

1. Connect the transmitter to the communication by contact or contactless method.

When possible, the preference should be given to the contact method of connection, which allows to perform the cable route location for more distantly.

2. Turn on the transmitter. Set the signal type - impulse **«Co»**/continuous **«Pu»** The generation frequency on the transmitter - 512, 1024, 8192, 32768 Hz.

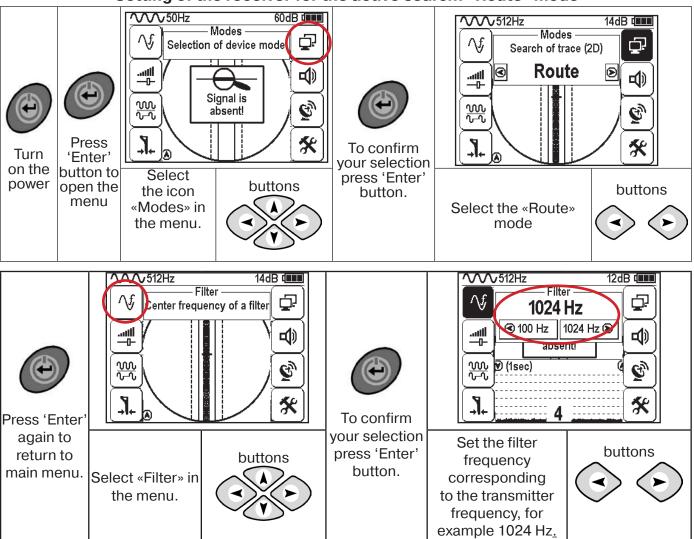
Impulse mode (Co) It is used to increase the time of work of transmitter.

Continuous signal (Pu) allows to conduct simultaneously with the routing the diagnostic of the faults of the power cable

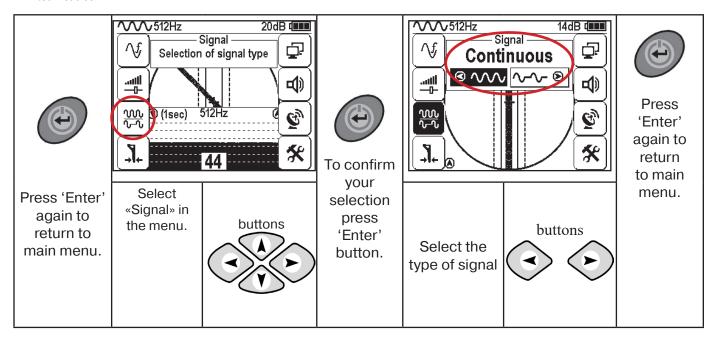
3. Start the generation, wait for the transmitter to power up.

4. Proceed with the setting of the receiver AP-019.3.

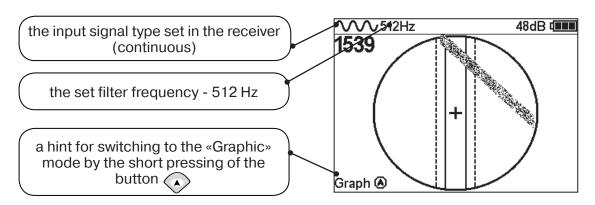
Setting of the receiver for the active search. «Route» mode







View of the receiver screen for route location in the active mode



Having set up the receiver, you can start locating communication and determine its burial depth **similarly to p. 5.2 (page 21)**



When working in the Route mode, sometimes happens the following:

- the positioning of the communication axis into the centre is impossible
 - the presence of several near located communications
 - low signal in the cable

in such cases you should switch to the «Graphic» mode.



5. Search of communications in the mode «Graphic»

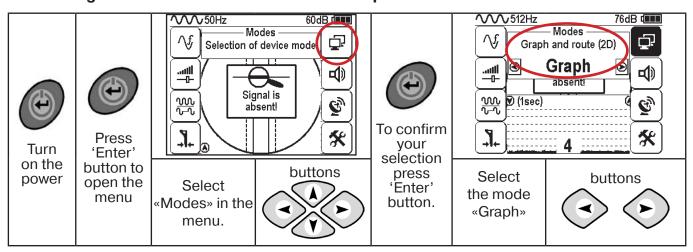
The **Graphic** mode is the support mode and intended to locate various communications (cables, pipelines), both in the passive and active modes with the route locating transmitter. In the passive mode the cable location is carried out at frequencies **50(60)**, **100(120)Hz**, in the active mode - **512,1024, 8192, 32768 Hz**.

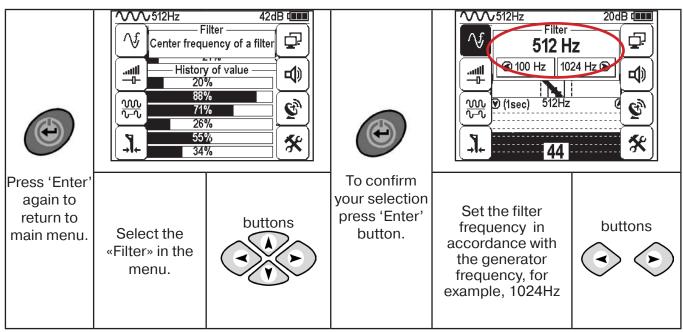
The **Graphic** mode is also intended to determine the number of the near located communications. The **Graphic** mode allows to perform the route location in the conditions of the low signal on the communication, when the route location in the **Route** mode is impossible.

The measurement of the burial depth and current is not available in this mode.

In the **"Graphic"** mode, the receiver screen displays the moving diagram of change in the signal level depending on the time by the 'maximum' method - when located over the communication the signal is maximum, when deviating from the axis - the signal decreases.

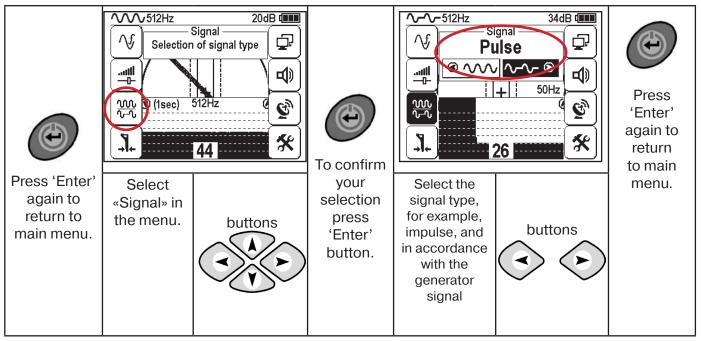
5.1 Setting of the receiver for work in the «Graph» mode





At the active search, the signal should be transmitted on the route from the generator with the same frequency as on the receiver (p.5.3).

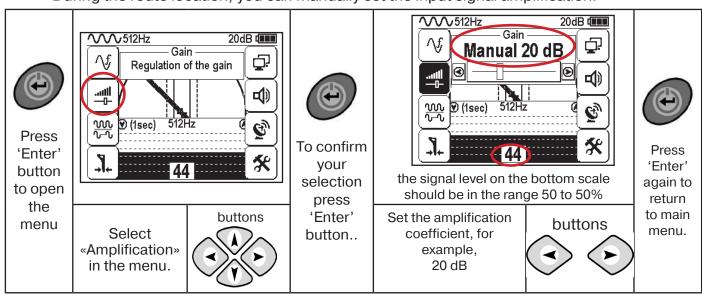
In the **"Graphic"** mode the work is performed in the **"Continuous"** or **"Impulse"** signal. The difference at the work with the **"Impulse"** signal is in that the digit in the center of the analogue scale shows not the current value of the signal, but the maximum value (amplitude) of the transmissions of the interruptible signal from the route locating transmitter. The pitch of the tone of the sound synthesized also corresponds to the maximum value of the signal for the period of the impulse transmitted.



When working in the passive mode **50(60) Hz**, **100(120) Hz** - you should always select the **continuous type of the signal**.

When working with the generator (in the **active mode**) **512**, **1024**, **8192** Hz, **33** kHz - the type of the signal on the receiver is **continuous or impulse**, in accordance with the signal set on the transmitter.

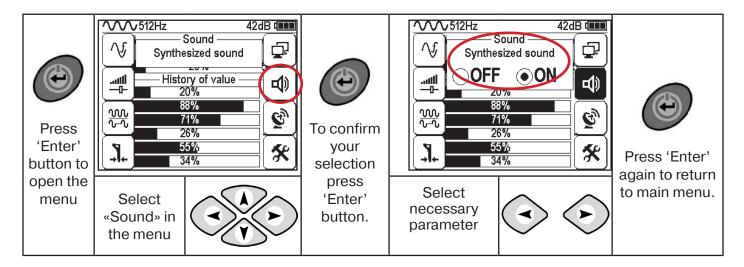
During the route location, you can manually set the input signal amplification.



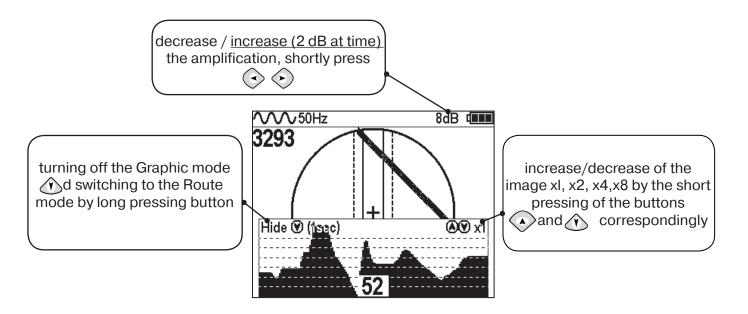
The change of the input signal amplification coefficient should be performed manually by short pressing buttons or semi-automatically by holding one of them pressed for 1 sec.

In the «Graphic» mode it is possible to listen synthesized sound through the built-in speaker, The sound tone pitch changes depending on the signal level.





5.2. «Hot» keys for work in the «Graphic» mode



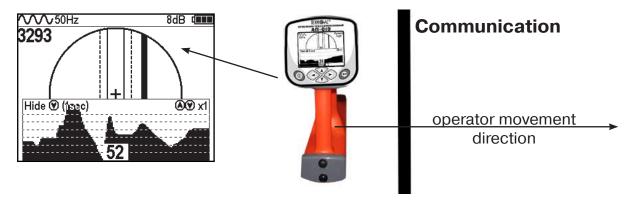
- If the signal occupies the whole graphic (the black string) it is necessary to perform the following actions:
- 1. Decrease the graphic scale to the value x1 by pressing button \(\hat{\chi} \)
- 2.Decrease the signal amplification coefficient by pressing button till the appearance of the decrease of the input signal level will be less than 80%.
- 3.In case of low signal, increase the amplification coefficient by pressing button and the scale by pressing button.



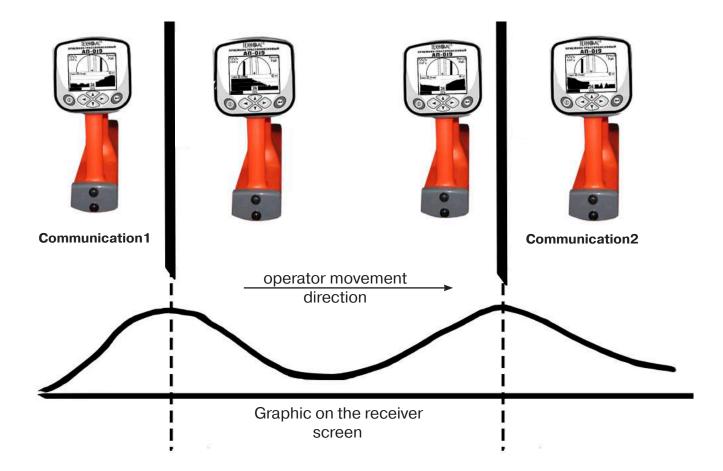
5.3. Search of communications in the mode «Graph»

- 1. Perform the receiver setting select the Graphic mode
- 2. Locate the receiver in parallel to the supposed axis of the communication, slowly move in direction as shown on the figure.
- 3. Slowly move the receiver towards the area where you had problems with locating the utility earlier.

You can see the example of operation on this picture:



At presence of two communications, the approximate view of the graphic on the receiver screen is given on the figure:



4. You should locate the place of communication by the maximum signal level.



6. Search of the utilities in the mode « Graphic+»

The «Graphic+» mode is available in the advanced set of modes. The «Graphic+» is the auxiliary mode. This mode differs from the mode «Graphic», it shows «2D» image compatible with the graphic, not the relative position of the route, but automatically demonstrates the presence and provision of the near «power» cable under the voltage with the frequency 50(60) Hz.

6.1. Setting of the receiver for work in the «Graphic+» mode

The setting of the receiver and use of the «hot keys» for work in the mode «Graphic+» is fully matches with the setting of the receiver for the «Graphic» mode, **section 6.1**, **section 6.2**

Note

6.2. Search of communications in the mode «Graphic+»

1. Connect the transmitter to the communication by contact or contactless method.

When possible, the preference should be given to the contact method of connection, which allows to conduct the cable route location more distantly.

2. Turn on the transmitter. Set the signal type - impulse «Pu»/continuous «Co» The generation frequency on the generator - 512, 1024, 8192, 32768 Hz.

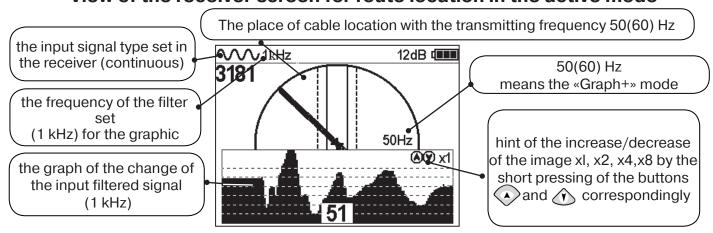
Impulse mode is used to increase the time of work of generator.

Continuous signal allows to perform simultaneously with the routing the diagnostic of the faults of the power cable.

3. Set up the receiver for work in the **"Graphic+"** mode (section 6.1), set the frequency and type of the signal the same as on the transmitter.

4. Start the generation, wait for the transmitter to power up.

View of the receiver screen for route location in the active mode



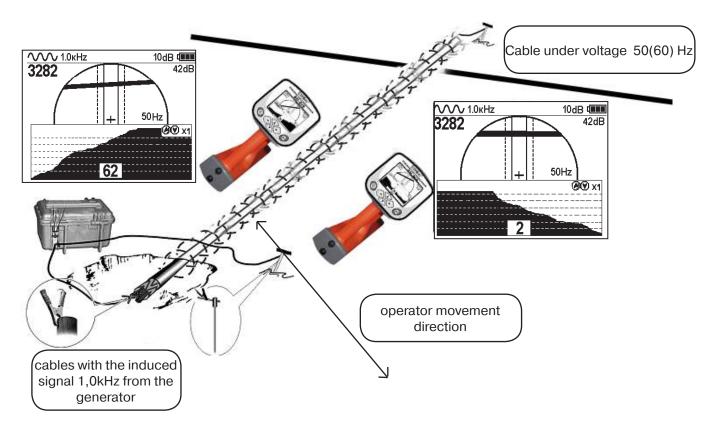
19



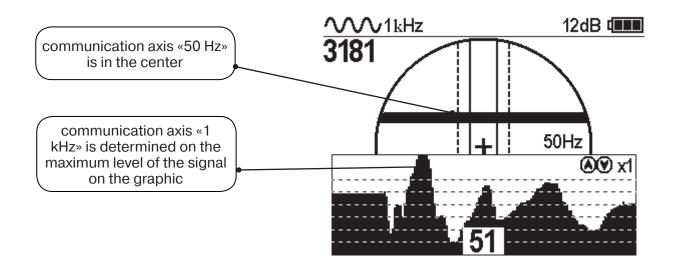
5. Approach to the supposed place of cable route, on which the signal from the generator was transmitted. Locate the receiver axis in parallel to the communication axis.

The graphic of change of the signal level will be displayed on the screen in frequency 512 Hz, on the 2D image of the route of the cable located near (if any) will be displayed under the voltage 50(60)Hz.

You should move the receiver as shown on the figure.



The place of crossing of cable corresponds to the setting of the pointer «50 Hz» onto the center of the circle at maximum value of the indication on the «Graphic» of the active frequency signal.



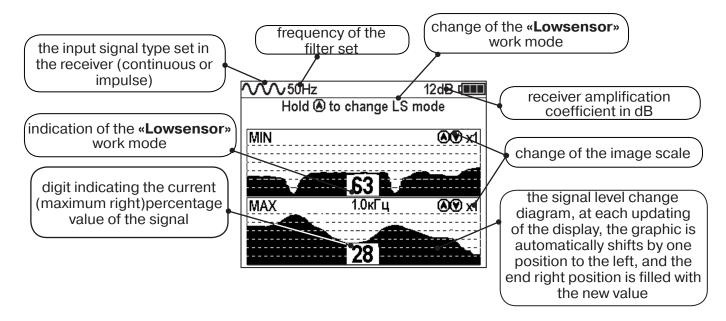


7. Perfoming the cable location in the mode «MIN & MAX»

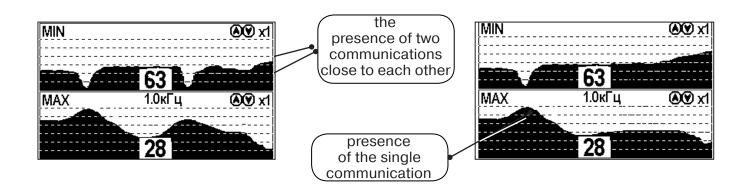
In the mode **«MIN & MAX»**, the device works simultaneously both on the method «maximum» and method **«minimum»**. This mode is used in the conditions of distorted field, in the presence of the nearby utilities, at the low induced signal. It allows to perform location, to determine presence and location of the utilities located nearby.

In the **«MIN & MAX»** mode the receiver display is divided in two halves. The moving diagram of the signal level change is displayed in the upper part by the **«minimum»** method - when located over the cable the signal is minimal, when deviating from the axis - the signal increases, in the bottom part - the moving diagram of the signal level change depending on the time by the «maximum» method - when you stand over the cable, the signal is maximum, when deviating from the axis - the signal decreases.

In this mode the value of the depth and current in the communication are not displayed.



The cable route location shall be performed similarly to route location in the Graphic mode, orienting on the maximum level of the signal on the lower scale of the graphic and minimum level of the signal on the upper scale. To determine the number of the nearby communications, you should step aside from the axis of the located cable and go straight across to the communication axis to visualize the amount and place of the route of communications.





8. Performing cable route location in the mode «2 frequencies»

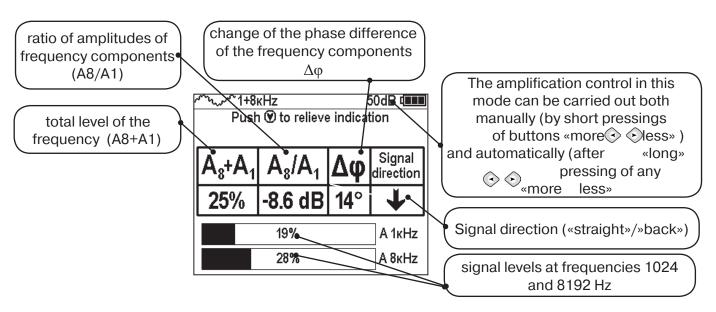
The mode «2 frequencies» was added for determination of the signal direction in cable. Additional possibilities of the mode are described in App. 2:

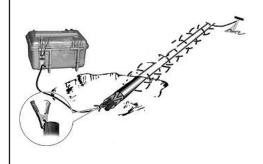
Append. 2 p.3 Amplitude «two-frequency» method «△A»;

Append. 2 p.4 Phase «two-frequency» «Δφ»



The mode «2 frequencies» is realized only with the contact method of connection of the transmitter

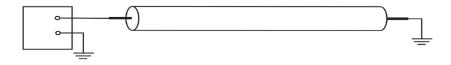




1. One output of the transmitter should be connected to the point of communication that more distant from the supposed place of the defect (start of the diagnostic site). The other output of the generator is grounded on the maximum possible distance from the communication. From the other side (end of the diagnostics site), the communication is grounded at the most possible distance from the communication.

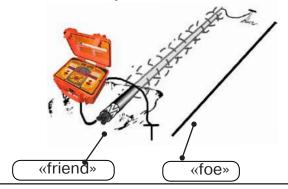
2. The transmitter in the mode «2F» sends to the communication the signals of two frequencies (1024Hz and 8192Hz) simultaneously.



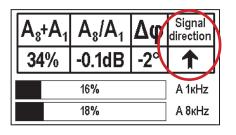




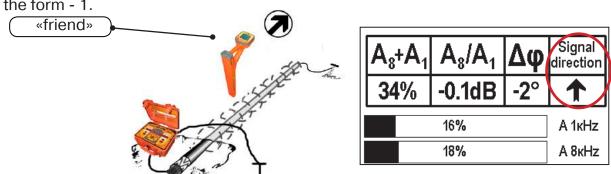
3. The signal from the communication, to which the route locating transmitter is directly connected, is conventionally named - «friend». The «parasitic» signal from the nearest communication, on which the generator signal is transferred, in conventionally named as «somebody else's».



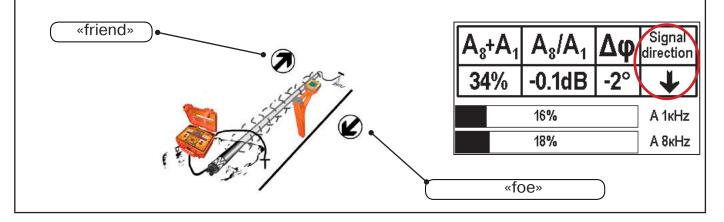
4. Based on the direction of the «arrow» it is possible to distinct «friend» signal from «foe» one, since the current direction in «friend» communication is opposite the «transferred» currents flowing through «foe» communications.



5. «Signal direction - forward» is the conventional concept and «assigned» by the operator for this position of the sensor relative to the this route. The «assignment» is performed by the pressing of the button « • », when the sensor is located exactly over the «allocated» communication, that is supposed to be «friend». After that, the pointer of the signal direction takes the form - 1.



When switching to the «foe» communication with the other «signal direction» (or at the change of the sensor position to the «reverse») the sound will be emitted (if switched on) and the arrow will show the «signal direction - back 1».

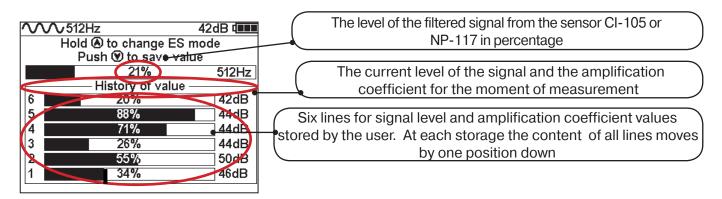




9. The work mode «Cable selection from a bunch»

The mode «Cable selection from a bundle» is switched on and off automatically at the connection and disconnection of the external sensor **(ES) CI-105** (inductive clamps) or **NP-117** (superimposed frame).

The mode is intended for selection of the «allocated» cable from the bundle of cables on the characteristics (maximum) signal emitted by this cable. The selection can be carried out at all the frequencies supported by the receiver.



9.1. The work with the receiver in the mode «Selection of the cable from a bunch»

Attention! In order to select the allocated cable from a bundle, you should provide the flowing of the current of the set frequency and form through it. To do this, it is necessary send into the searchable cable the signal from the route locating generator by the contact or contactless method and provide the «current return» to the generator (for example, through the ground). All output ends of cables of the bundle should be connected to the «return» circuit.

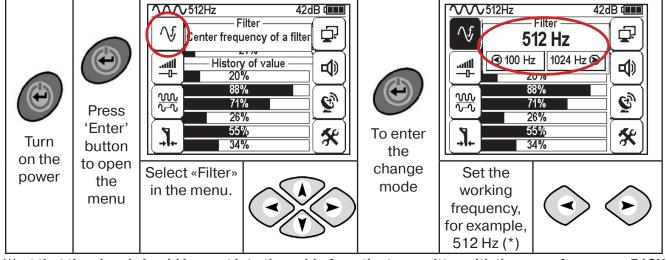




105 using the cable -adapter for pliers to the receiver (fig. 9.1) or NP-117 (fig. 9.2).

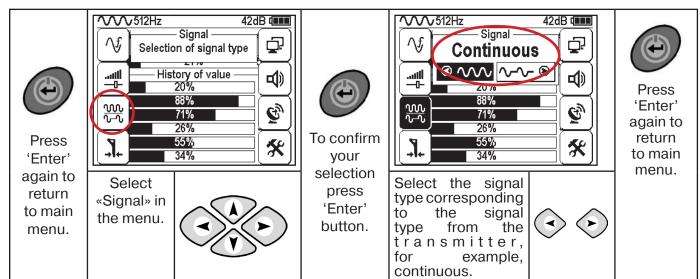
Connect inductive «clamps» CI-

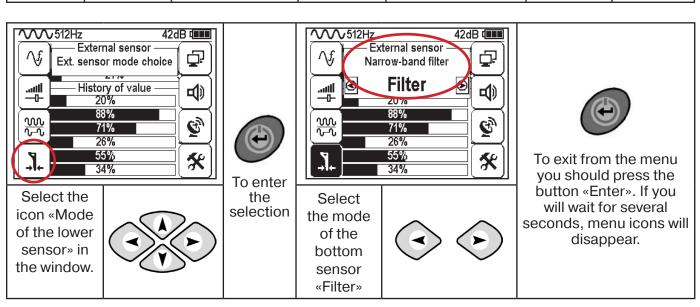
Fig.9.1 Fig 9.2



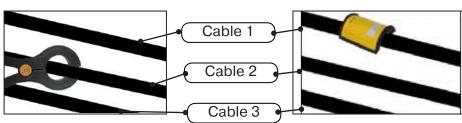
(*) at that the signal should be sent into the cable from the transmitter with the same frequency 512Hz

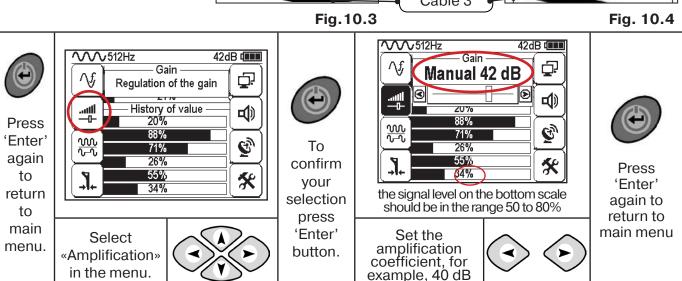


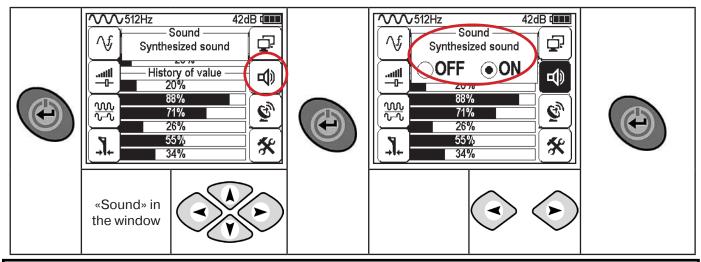




Install on «induction clamps» CI-105/110/110 (fig. 10.3) or apply NP-117 (fig. 10.4) onto the one of cables.







Save parameters of measurement into the memory by pressing the button (1)



Alternately putting on «Inductive clamps» or applying a attachable frame to the cables bundle, find «isolated» cable by the higher level of the signal (Fig. 10.5).

The tone pitch of the synthesised sound correspond to the signal value (including and «impulse» amplitude)

Cable 1 Cable 2 Cable 3

To compare the signals, you should measurements at the equal amplification coefficient.

In the example (fig. 10.5) it is possible to compare values only with the amplification 42 dB. The maximum of them is the value under the number 5.

> The maximum signal 80% (42 dB) corresponds to the cable No.2

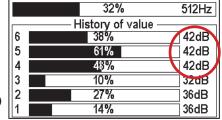
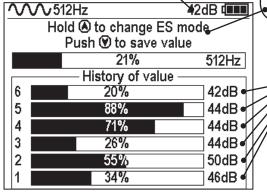


Fig. 9.5

9.2. «Hot» keys for the work in the mode «Selection of the cable from the bunch»

step-by-step (by 2dB) decrease / increase coefficient of the amplification, sequential pressings

switching between modes of work of the external sensor (ES) is carried out by the holding of the button more than 1 sec. «WB» - range of frequencies 0.04..8 kHz. «Radio» - range of frequencies 8..40 kHz at absence of the value corresponds to the frequency of the set filter (here - 512 Hz)



The storage of the parameters of measurement (signal level from the sensor connected and amplification coefficient) into the memory using the button

(the memory keeps last six measurements)

Note

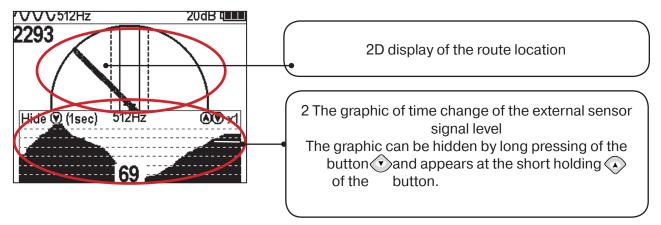
In the mode «Cable selection from a bunch» using the external sensor, the work with the continues and impulse signal is supported (menu option «signal», table 1 p.3). The difference at the work with the «Impulse» signal is in that the digit in the center of the analogous scale shows not the current value of the signal, but the maximum value (amplitude) of the transmissions of the interruptible signal from the route locating transmitter made by TECHNO-AC.



10. Mode «Search of defects» using external sensors

The mode 'Search of defects' is switched on and off automatically, when connecting and disconnecting external sensors DKI-117, DOLK-117. The mode «Search for defects» with external sensors DKI-117/DODK-117 was added for search of insulation defects.

The search of defects of cable defects can be carried out at all frequencies both in an active, and passive modes.



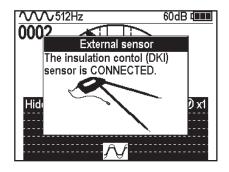
10.1. The work with the receiver in the mode «Search for defects»

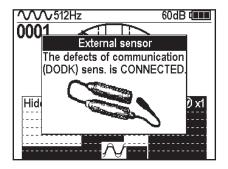




Fig. 10.1

Fig. 10.2



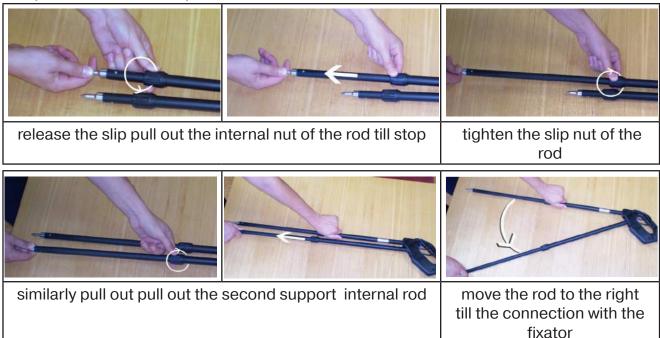


- Connect to the sensor to the receiver of the insulation control DKI-117 (fig. 10.1) or DODK-117 (fig. 10.2).

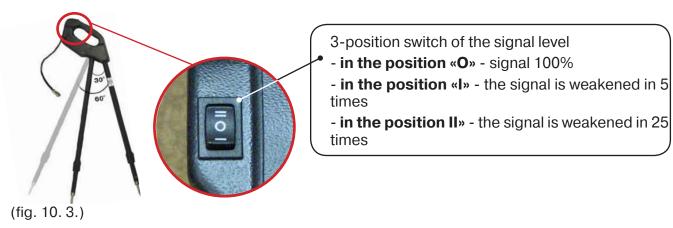


Preparation of the sensors for work DKI-117

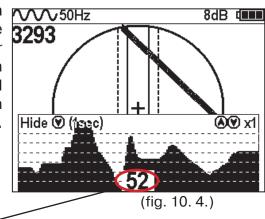
Prepare the sensor for operation.



The average position of the fixator corresponds to the angle 30, end - angle 60 (fig. 10.3). Maximum distance between electrodes corresponds to the maximum sensibility.



Before starting the operation you should set the switch into the position «O». If during the search process, with the amplification coefficient 0 dB, the input signal level is greater than 70%, you should switch the sensor regulator to «I» position and with a further increase of the signal to the position «II», and then perform the adjustment of the coefficient of amplification of the receiver to the level of the input signal 50 to 80%. (Fig. 10.4)





DODK-117

The survey shall be performed by two operators, the one operator has the measuring electrode, and the second one has the measuring electrode and receiver (fig. 10.5). Based on the receiver indications, you can locate the damaged cable (by methods described in the application 2 p.1-2).

NOTICE!

When working with the sensor DODK, the electrodes should be used without gloves, providing the contact of the sensor with a skin (fig. 10.6)



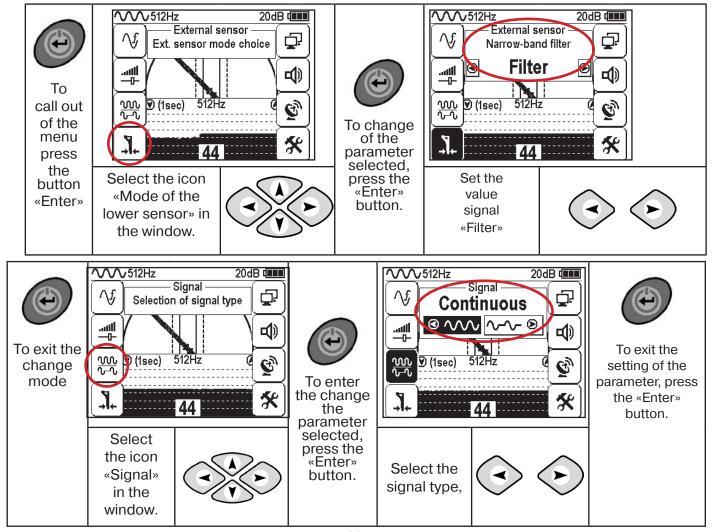


Fig. 10.6

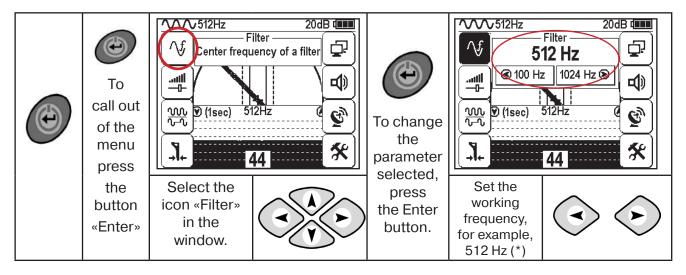
Fig. 10.5

Receiver setting

- 1. Turn on the receiver
- 2. Set the work mode of the lower sensor to the value «Filter»
- 3. Set the working frequency and type of the signal:

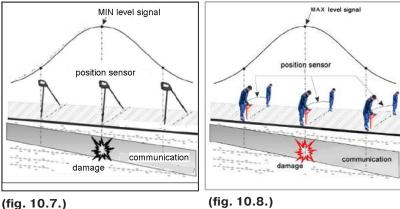




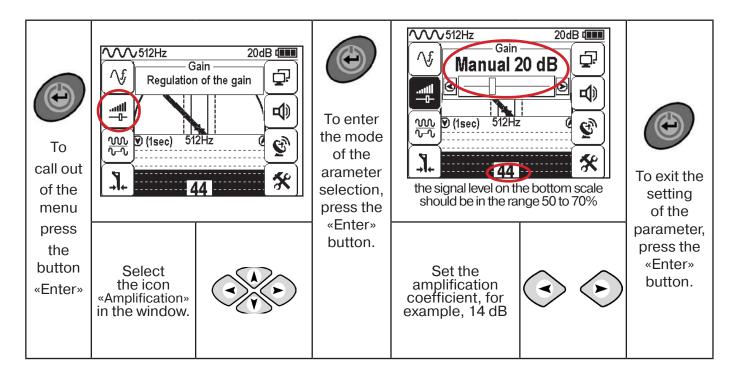


Wait for several seconds till menu icons disappear

The search of insulation damage should be started by the method «MAX» (fig. 10.7, 10.8) (see. appendix 2). Move along the cable axis, mark the place cable signal (start of the signal rise, place of the maximum detection).

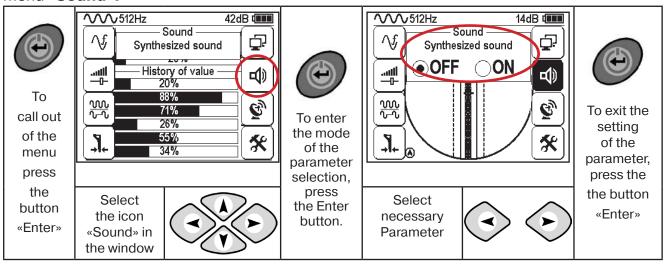


When working with sensors you should regulate the receiver amplification coefficient so that the signal level was in the rang 50 to 90 %.

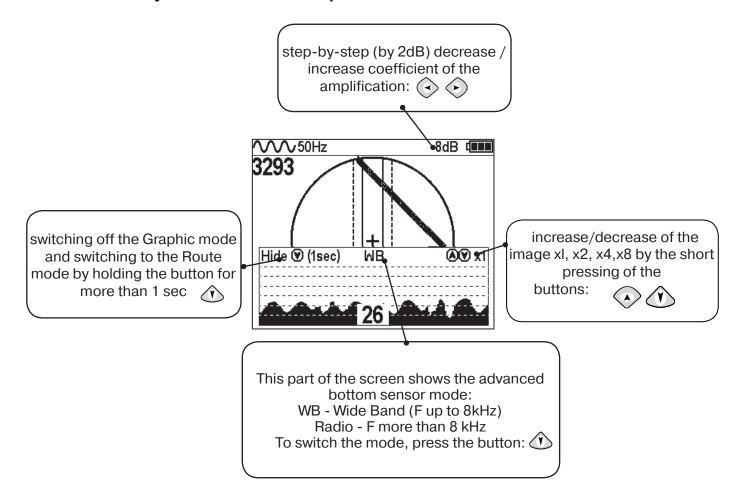




The user can listen synthesized sound through the built-in sound speaker. The sound tone pitch changes depending on the signal level. The synthesized sound can be switched on in the menu **«Sound».**



10.2 «Hot» keys for work in the «Graphic» mode with DODK and DKI

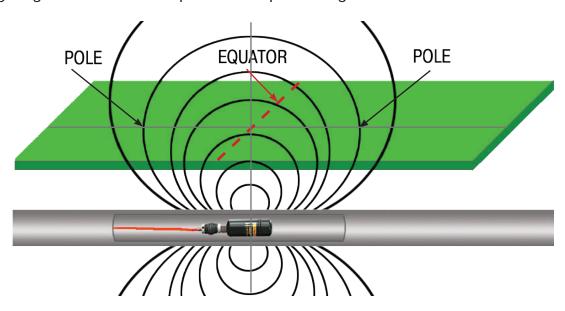




11. Sonde mode

Sonde operating principle

Sondes (also known as beacons or pipe transmitters) have built-in emitting coil which generates alternating magnetic field with two poles and equator on ground surface:

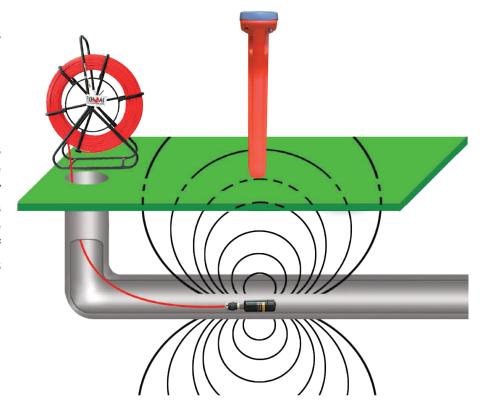


It is known that position of the poles and equator is always constant, that is why this characteristics are used for precise location of pipe sonde position.

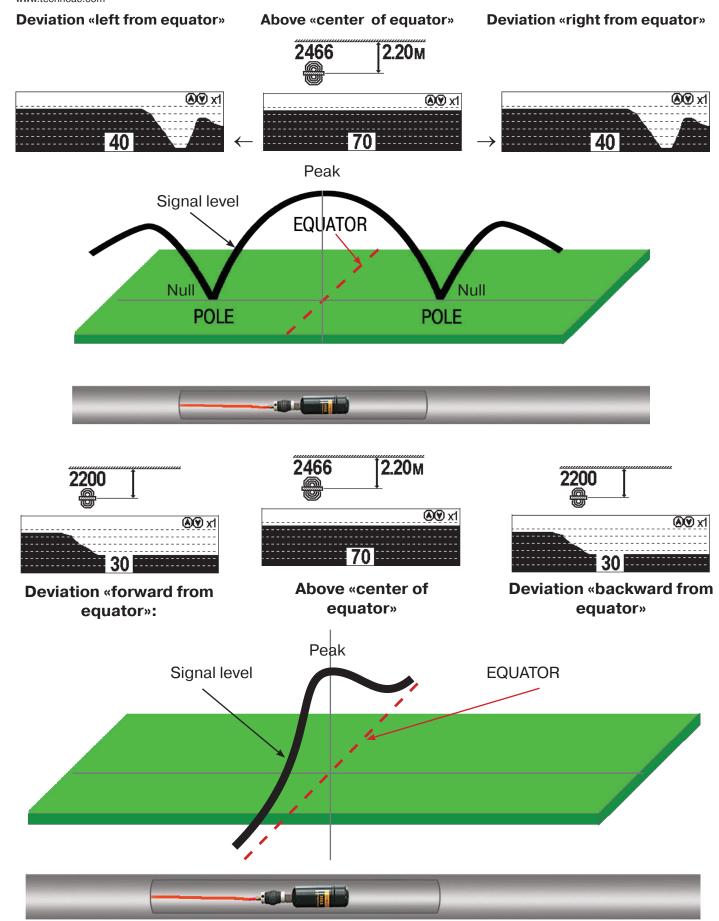
The sonde is inserted into the pipeline with push wire.

The locator scans the signal from the sonde and detects its position and burial depth.

To get maximum signal level is a key goal of locating sonde's position. Burial depth of the sonde is indicated correctly only when the receiver is positioned strictly above the sonde (above the center of equator) and the sonde is positioned horizontally.







Signal of horizontally positioned sonde as it is seen by EM sensor of the receiver.

"Main peak" (general maximum) is situated above the center of sonde's emitting coil (equator's center), and two 'false peaks' (local maximums) they are situated before two "nulls" (minimums or poles).



11.1. SONDE DETECTION AND LOCATION OF THE UTILITY

- 1. Select «Sonde» mode in menu.
- 2. Before installation the sonde into the utility, make sure that sonde is fully operational and receiver can obtain strong and stable signal.
- 3. Mount the sonde on the push wire using 3.5 mm hex head (not included in supply). You have to match the hole on the wire with the mounting hole on the sonde.
- 4. Push the sonde into the pipe. In order to start location, you have to push it not less than 3 m from the operator.

You have to stay within the filed, generated by the sonde in order to locate it. Field range depends on the type of sonde, pipe material, depth and soil type.

To locate the Sonde, find the area with maximum signal level.

5. To locate the approximate direction of the sonde, point the locator on the utility and search the area for signal, slowly moving the locator perpendicular to the ground around the spot.

By looking at maximum value of four-digit number on receiver display, you can see the signal level.

Signal level reaches its maximum, when lower antenna is positioned as close as it is possible to the sonde. Sound indication of the receiver will help to locate the spot of the maximum signal.

The signal will be maximum when locator's axis will be perpendicular to sonde's axis.(utili-ty axis) and the locator will be pointing at the sonde.

When approaching to the sonde, the signal level will be rising. (together with the tone of sound indication)

6. When approximate direction of the sonde is located, position the device strictly perpendicular to the utility axis and walk in sonde's direction.

At the point of maximal signal, the locator, pointed strictly perpendicular to the utility should be moved along the equator line until it reaches maximum signal point.

7. When the receiver is positioned like in minute 8, try to move it left, then right in order to locate false peaks. Each peak consist of two signal values: one with critical signal level rising and the second with some signal level rising. If these local false peaks are presented in the area and the sonde has horizontal orientation, it means that the locator is positioned strictly over the sonde and that you've located the utility.

NOTE: Do not forget to mark the location of the sonde and check the depth. (Press "down" button for 1 second)

8. Continue to locate the route: consequently push the sonde at 2-4 meters, move the locator along the route and locate the sonde as it was written in minutes 7 and 8.

NOTE

The place with maximum signal, generated by the declined sonde can be positioned off the equator line. (see 'Declined sonde' for more information)

ATTENTION!

Standing on the equator doesn't mean that you are standing over the sonde.

Remember, that key goal of locating the sonde is locate the spot with maximum signal.

You have to be at the point of the strongest signal in order to locate the sonde.

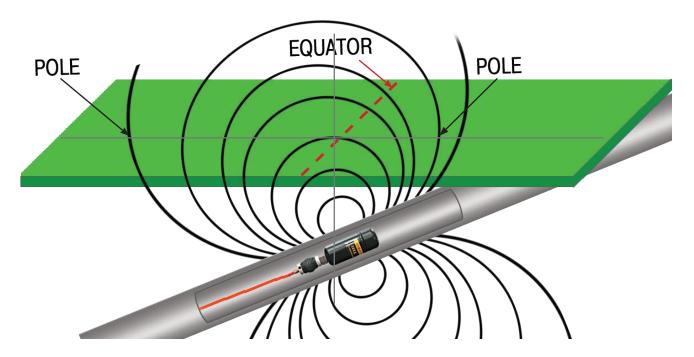


11.2. DECLINED SONDE

The sonde is considered as declined when its position is not parallel to horizontal ground surface. It commonly happens if the utility changes its vertical direction. Finding the poles of equator can help figuring out if the sonde is declined or not.

When the sonde is declined, the equator will be positioned not in the middle between two poles. When the sonde is significantly declined the equator can be positioned off sonde's center and the maximum signal point can be positioned near one of the poles.

Sometimes, when the sonde is positioned strictly vertically (perpendicular to ground sur-face) one of the poles will be positioned strictly together with max signal point. The second pole will not be visible at all. In any case, in order to locate the position of the sonde, find the spot with maximum signal level.



11.3. MEASURING THE DEPTH OF THE SONDE ATTENTION!

The receiver must be switched to Sonde mode, ecause electromagnetic field, generated by the sonde has complex 2-line quasi-toric form.

- 1. In order to measure the depth, you have to position the locator perpendicular to the ground, strictly over the sonde. You have to slowly move the device around, in order to get the best signal and best depth reading.
- 2. Press and hold "down" button on the locator for 1 second. It will enable the depth measure-ment. Measured depth will appear on the screen.

In order to confirm the readings of the depth, you have to do the following:):

- 1. Remember the depth value you've just received.
- 2. Raise the locator at 150mm above ground surface.
- 3. Look at the depth change. The depth should increase on 150mm.

If the depth value remains the same or increased more than it was intended, it can mean the following: signal field is distorted, the signal is too low (for example, the batteries of the sonde are dying), wrong location of sonde's signal equator. (the original depth was measured at wrong place.)

NOTE: Use the depth value only as approximate reference. Before ground works, try to measure burial depth of located utility with any available method.



Appendix 1 Receiver AP-019.3 Specifications

Parameter	Value	
Receiver filter centre frequency	Switching 50(60)/ 100(120)/ 512/ 1024/ 8192 / 32768 Hz	
«Wide band»frequency band	0,048 kHz	
Frequency range "Radio"	840 kHz	
Maximum amplification factor of the electric path/dynamic range of the input signal	>120 dB	
Number of embedded sensors	4	
Max. Sensitivity	5 mkA at 1m distance (at 33 kHz)	
Selectivity	Q _{-3 dB} >100 stopband supression up to 120 dB	
Data log capacity	> 2000 «points»	
Sensors type	Inductive	
Sensitivity control	Auto - for 2D display «Route». Semi-automatic or manual (optional) - for the «Graphics». Automatic or manual (optional) - for the «2F» mode.	
Determination the burial depth of the route	Automatically in «Route mode» 09,99 m	
Laying depth identification accuracy	±5%	
Identification of the effective current in the route	Automatically in «Route mode» 0.0019,99 A	
Accuracy of identification of the current of the effective current in the route	±5%	
Support of energy saving (intermittent) modes of the route locating generators	At combined work with the route locating generators made by "TECHNO-AC" ("Pulse" mode)	
Visual indication	Graphic display LCD display, 320x240 pix., with LED backlight	
Induced parameters	-parameters of setting and control - 2D visualization of the route location relative to the device -graphics of the signal level from sensors - route burial depth - signal current	
Audio indication	Headphones: -natural filtered sound	
Addio indication	Built-in transmitter - synthesized sound HM- sound indication of buttons pressing	
Permissible impedance of the headphones	min.32 Ohm	
Power source	47 V (4 type C batteries)	
Time of continuous operation from the single battery set	Not less than 20 hours	
Automatic shutdown when the device is not active	After 30 minutes of inactivity	
Operating /storage temperature range	-2060 / -3060°C	
Dust and water protection degree	IP54	
Dimensions	330x140x700 mm	
Weight	2,45 kg	



Appendix 2 Searching methods by AP-019.3

1. MAX method when searching the place of insulation damage with sensors DKI-117 and DODK-117

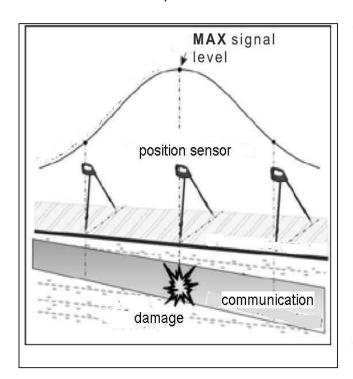
When searching for insulation damage by **«MAX»** method, the one of the input terminals (contact pins of DKI or electrodes of DODK) should be placed over the route, and the second one - at a maximum distance from the route, in the direction straight across its axis.

While moving along the route, the operator dips the contact pins in of DKI sensor in the ground. The measurements will be correct while the contact pins are firmly dipped into the soil.

DODK electrodes are transported by the two operators located from each other at the distance equal to the length of the connecting wire. In this case, measurements can be made continuously in motion.

The signal gradually increases when approaching the spot of damage, reaches it's maximum when one of the contact electrodes is above the damage spot and then gradually decreases (fig.A.1).

The MAX method can reliably detect the existance of damage, however, has a low accuracy of localization of the exact place due to the blurred indication of signal curve maximum.



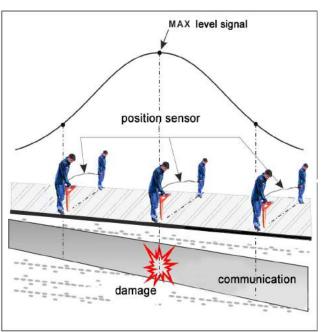


Fig. A.1



2. Method MIN when searching the place of damage location using sensors DKI-117 or DODK-117

When searching for insulation damages by **MIN** method, the contact pins of DKI-117 or DODK-117 electrodes should be placed over the route, along the axis of the route. When you use the MIN method, the signal increases smoothly at first, then rapidly decreases to a certain minimum value, then as the distance from the damage place increases, it rises sharply again and then gradually decreases.

The place of damage will be located midway between the electrodes, at a time when the signal reaches the minimum value (fig. A.2).

The sensor DODK-117 provides a "fast" method of damage location, which is especially important for the extensive communications, and the sensor DKI-117 provides a higher sensitivity and accuracy of damage location and needs only one operator for work with it.

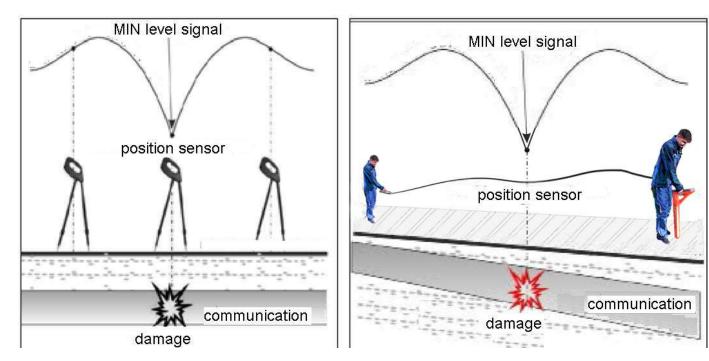


Fig. A.2

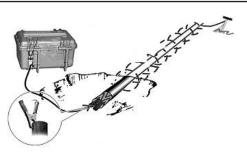


3. Amplitude «two-frequency» method «AA»

This method was added for contactless search of insulation defects of city cables with resistance less than 5 kOhm. The smaller the distance to the end of the cable, the higher the sensitivity of the method on this site.

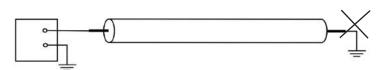
The method decription: the two-frequency signal is transmitted from the generator. The ratio of two-frequency signal amplitudes remains stable, if there is no damages in cable. At presence of damage, the ratio of amplitudes in the place of damage is changed.

Table 8



of 1. Exit output the generator should be connected to the «start» of communication (more distant from the supposed place of the defect). The other output of the generator is grounded on

the maximum possible distance from the communication. The «end» of the communication is not grounded.



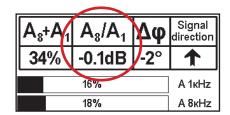
2. The transmitter in the mode «2F» sends to the communication the signals of two frequencies (1024Hz and 8192Hz) simultaneously.



3. The defect localisation is performed in direction «from generator».



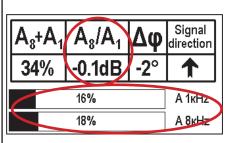
4. The value «A8/A1» is sharply changes, when operator passes the place of leakage of the signal current into the ground.



Note

A8/A1 indication can have negative value. In such cases it recommended to reset indication periodically, using the button



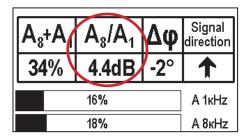


The «double» scale shows 5. levels (amplitudes) of the frequency components of the signal. At bottom - «A8kHz», at top - «A1kHz». When levels of the frequency components are insufficient for determination «Δφ», the inscriptions «A8kHz» and «A1kHz» are correspondingly the «darkening», and value «X.XdB» disappears.

6. There is no need to continuously move along the route, controlling the signal. You can walk around the place which is hard to reach. If, while returning to the route, A8/A1 did not changed, it means that there are no damages on the surveyed site.

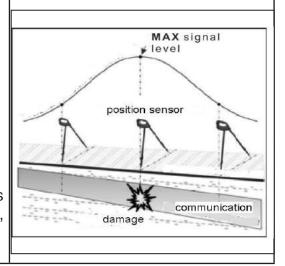


7. The sharp positive overfall of the « $\Delta \phi$ » value by 3dB and more indicates the possibility of defect existance(the resistance is less than 5 kOhm). The sensor should be located straight across the communication.



If you go through the same site in the opposite direction (towards the generator), holding the receiver the same as before with reset of the indication (using the button «①»), negative value of the reading (more than minus 3dB) will mean that there is damage in the cable.

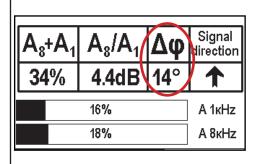
8. To validate the existance of the damage, use 2contact method, using. (the methodology in app. 2 of p.1.2)



4. Phase «two-frequency» method « $\Delta \varphi$ »

The contactless method of search for insulation defects of city cables with resistance less than 10 kOhm. The smaller the distance till the end of the cable, the higher the sensitivity of the method on this site. This method cannot be used in city because of high distortion of the signal.

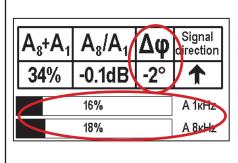
Steps 1-3 are similar to those in p.3.



4. « $\Delta \phi$ » shows - the change of the phase difference « ϕ 1024 — ϕ 8192», after the resetting (in degrees reduced to the frequency 1024 Hz). The value « $\Delta \phi$ » is sharply changes, when operator passes the place of leakage of the signaling current into the ground.

Note

 $\Delta \phi$ indication can be negative, «running» in the process of increase of distance from the generator. It is recommended to periodically reset such indications (exactly over the route), using the button « \diamondsuit ».

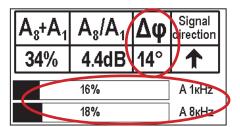


5. The «doubled» scale shows levels (amplitudes) of the frequency components the signal. At bottom - A8kHz, at top - A1kHz. When levels of the frequency components are insufficient for determination $\Delta \varphi$, the inscriptions A8kHz and A1kHz are correspondingly «darkening», and the value «X⁰» disappears.

6. There is no need to continuously move along the route, controlling the signal. You can walk around the place which is hard to reach. If, while returning to the route, " $\Delta \phi$ " did not changed, it means that there are no damages on the surveyed site.

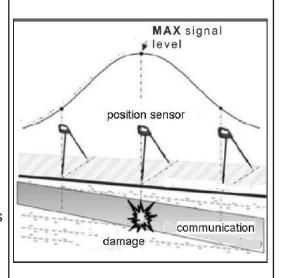


The sharp positive overfall of the « $\Delta \phi$ » value by 5° and more indicates the possibility of defect existance (the resistance is less than 10 kOhm). The sensor should be located straight across the communication.



If you go through the same site in the opposite direction (towards the generator), holding the receiver the same as before with reset of the indication (using the button « **), negative value of the reading (more than minus 5°) will mean that there is damage in the cable.

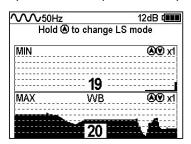
To validate the existance of the damage, use contact method, using. Append. 2 p.1,2)

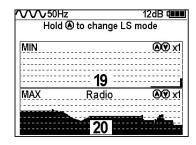




Appendix 3 Area survey before excavation works

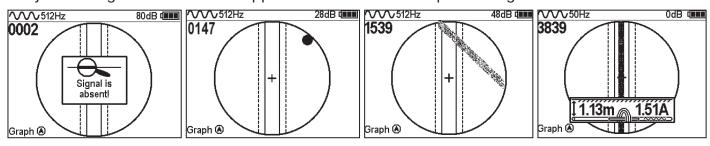
First of all the area should be surveyed with the receiver in passive mode, in order to locate the signal from energized power cables, pipes with cathodic protection or any other current providing utility. To do that, use the following frequencies consequently: 50 Hz, 100 Hz, Radio and Broadband mode. Area survey in broad band frequencies should be performed in "MIN&MAX" mode: In lower sensor mode WB (0-8kHz) and Radio (over 8kHz).



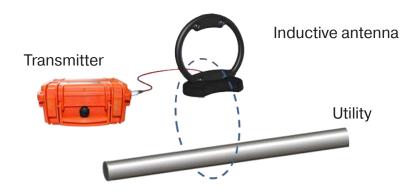


In this case the operator should rely on "MAX" scale.

At 50 a 100Hz frequencies in Route mode the signal strength will increase as you are moving to the utility. Following indication should appear on the screen while performing these actions:

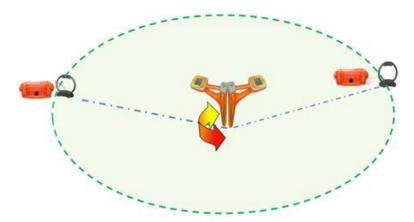


Active mode survey is performed with transmitter and external inductive Antenna IEM. Inductive antenna induce better signal when it is positioned in the same flatness as the utility.



First make sure that there is no utility in the center of surveyed area. To do that, first operator with receiver stands above the tested point and second operator moves the transmitter with antenna around the first one. The radius should be 10-20m and the first operator should point the head of receiver towards the 2nd operator with antenna.



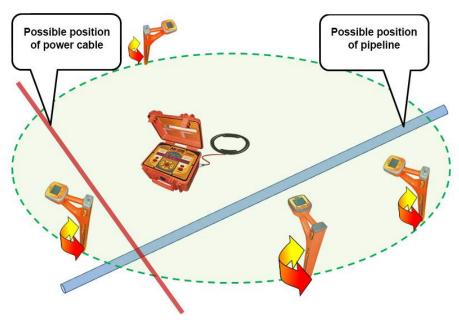


If there is no utility in center point of the area, then start the general location routine described below.

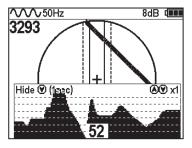
When surveying the area in active mode, it is necessary to place. IEM antenna horizontally in the center of the plot (you can remove the antenna from its stand). In this position the antenna will be in the flatness parallel to all surrounding utilities in the area.

After that it is necessary to connect the antenna to the transmitter and start the induction. Power of the transmitter should be set according to the size of the surveyed area (the smaller the area – the smaller the power).

Area survey in active mode should be carried out in "Graph" mode of receiver at the same frequency as had been set on the transmitter. Operator should move around the transmitter and perform to measurements at each point in two mutually perpendicular positions.



The presence of the utility will be indicated by the "signal strength" value (upper left part of display) or the graph in bottom part of the screen.





Appendix 4 Operational features of the set

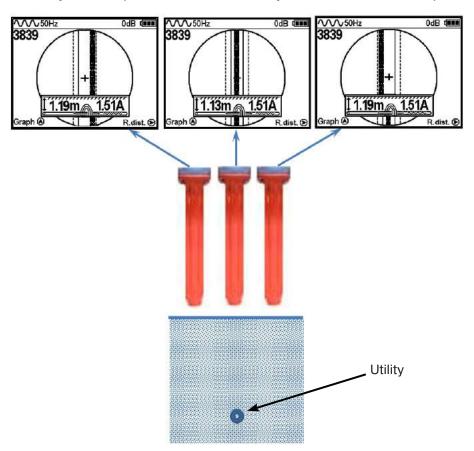
External influence during receiver operation

Receiver's display readings can be incorrect while operating in distorted electromagnetic field. The cause of that may be in closely (approx. 3m radius) positioned metal objects(cars, metal fences, manholes and other utilities) and mobile phones.

If an important measurement is going to take place, please, try to exclude the influence of surrounding distortion.

Specialties of utility depth measurements

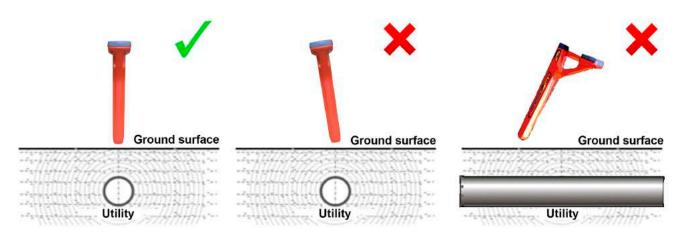
During depth measurement process (if the utility axis indication is in the area of receiver screen, including its aligning with the axis of receiver) if the receiver is slightly moved aside the value of depth is increasing. That is why, true depth will be indicated by minimum value of depth indication.





Receiver position during depth measurement

Before measuring the depth of the utility, make sure that your device is positioned perpendicular to the utility. Even slight deviation from vertical position can influence the precision of depth measurement.



Operation via external power supply

When operation is performed via external power supply, all internal power sources should be removed.

Specialties of utility location at 50Hz

50Hz signal is used almost in every electric supply system in Russia and in most European countries. Energized cables create electromagnetic fields, which are induced to other conducting utilities (pipelines, dead cables)

From one side, this allows operator to locate both pipelines and cables in "Route" mode. Operator can define power cable and pipelines according to the depth (as a rule, average depth for cables is 0.6-1.0m; for pipelines 1.5m and more)

From other side, electromagnetic fields, created by current, induced on pipelines make tracing harder, especially in the areas with a lot of utilities in one spot. The receiver evaluates the position of the utility according to the resultant signal in a given spot.

When operating in passive mode on 50Hz frequency, in case of multiple utilities, the receiver can't tell which emits the signal. In this situation the values of depth can be incorrect.

It is important to understand that separate cables under voltage can create very weak electromagnetic fields and as a result almost absent resultant signal. It may be impossible to locate them in "Route" mode . Please, use "Graph" mode to identify the position of such cable.



12 The transmitter AG-120 12.1 Appearance. Controls





Fig. 12.1

1	External power switch (mechanical waterproof) with generation indicator		
2	Button «①» control of internal electronic power switch		
3	Button of power supply parameter indication		
4	Indicated power supply parameter: voltage acc.1/acc.2/ext. power. (V), life time (hour) or charging time (hour, min)		
5	Menu control buttons		
	« « » - selection of parameter to be set in the left direction by the indicator		
	« 🕿 » - increase of value or «up» in the list		
	«		
	« » - selection of parameter to be set in the right direction by the indicator		
	« »: in the «stop» condition – entering to the parameter setting / exit from parameter setting with saving of settings - in the «generation» condition – input of current value of output current as setup		
	value		
6	Indicator of power supply parameters (V, hours), work mode, generation frequency (Hz), set current (A), output parameters (V/A/ Ω /W)		
7	«MATCHING»		
	(results): set current is achieved «Imatch», mode of unlimited voltage «U 📤 », maximum voltage «Umax», power limited at the optimal level «P lim»		
8	Parameter indicated by «output multimeter»: U «V», I «A», R «Ω» , P«W»		
9	Button of selection of parameter indicated by «output multimeter»		
10	Button « [▶] •»«START/STOP» of generation, matching or charging		
11	Transparent window for indication reading with closed cover		
12	Plug sealing the output connector (opened)		
13	Plug sealing the external power supply connector (closed)		
14	Output connector to connect the buried utility, transmitting antenna or clamp		
15	Input connector to connect external accumulator or mains power supply adapter (operation/charging)		



12.2 Procedure of work with the transmitter

SAFETY REQUIREMENTS

WARNING! Output port and leads of transmitter may carry dangerous voltage (more than 330V). The route detection procedure is based on the grounding of one of the transmitter output clamps.

NEVER! Touch the output connecting cables clamps and elements of the monitored buried utility when the transmitter is in operation.

NEVER! Connect and disconnect the connecting cables when the transmitter is in operation.

The persons properly instructed and having no medical restrictions are admitted for instrument operation.

Personnel safe procedure for work with the transmitter when connecting to the route:

- make sure on the monitored buried utility and near it no activities are conducted or planned which can result in deliberate or accidental touching of the current-conducting part under voltage;
 - make sure the generator is switched off;
- ground the cable conductor opposite to the transmitter connection point and put the table «Grounded» («High voltage»);
- make sure the instrument can not be activated accidentally by another person during connection of the output cable;
 - connect the output cable clamp to the monitored buried utility (cable wire, pipeline, link cable);
- connect the second clamp of the output cable to the grounding, cable armor or to the grounded rod;
 - connect the output cable connector to the output socket of the deactivated transmitter;
- if there are other persons near current conductive parts alert them about voltage supply by saying «Applying voltage ».

ATTENTION!! When connecting the transmitter the latter itself shall be TURNED OFF!!

Personnel safe procedure for work with the transmitter when disconnecting from the route

- turn off the transmitter power;
- disconnect the output cable from the transmitter and close the connector with rubber plug;
- conduct the troubleshooting activities only AFTER the transmitter is turned off and disconnected from the buried utility

When working on pipelines, use only "safe" mode!



12.3 Transmitter connection

1) Contact mode of transmitter connection

This mode guarantees transmission of signal without interference and allows use of low frequencies.

The connection to buried utility is done by mating of the output connector of the transmitter to the buried utility and grounding rod **figure 12.2.**

The grounding is carried out in any convenient place, which should be cleaned from the dirt with file or sand paper to the metal. This ensures more reliable contact of the clamp and buried utility.

Rules for grounding:

- To achieve the maximum tracing distance when the transmitter is connected to the buried utility the grounding shall be arranged at an angle close to 90° and **as far as possible** from the route in the assumed search direction.
 - The grounding rod shall be inserted for at least 2/3 of its height.
- Fig. 12.2

Fig. 12.2

- To achieve better grounding effect the following methods shall be used in the place of grounding rod installation: cleaning of contact in the place of contact wire connection to the ground rod, pressing of the ground, moistening of the ground using salt solution.

Methods of transmitter connection to the route

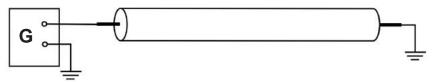
To achieve quality in route position detection the following rules should be observed:

The direct connection of the transmitter to the load provides the longest tracing distance.

Several ways can be used to define the underground cable (or pipeline) route when directly connected to the buried utility. They are as follows:

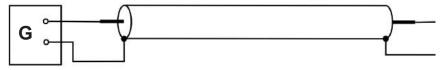
1) The ground is a return conductor

Connect the transmitter to one end of the cable, ground the other end of the cable.



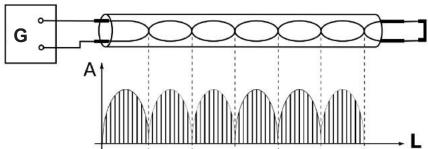
2) The cable armor is a return conductor

Connect the transmitter to ends of the cable; join the other ends of the cable.



3) The cable cord is a return conductor

Connect the transmitter to two cords from one end of the cable, join the cords from the opposite side.





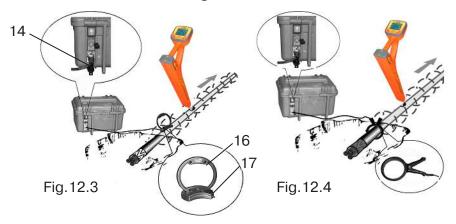
2) Contact free mode using the inductive antenna – IEM

Connecting to the utility is carried out by induction method.

To do this: remove the antenna from it package and insert active part of the antenna in the foundation body. Connect the antenna to the transmitter output connector (**pos. 14 figure 12.3**) and install over assumed place of route. The antenna and route must lay in the same plane.

3) Contact-free mode using the transmitting clamp.

Allows tracing of the selected buried utilities, energized and de-energized cables. The clamp shall be put around the conductor to be traced **figure 12.4.**



NEVER! Touch the clamps of connecting cables and parts of monitored buried utility while the transmitter is working.

NEVER! Mate and disconnect the connecting cables while the transmitter is working.

12.4 Turning on the transmitter power

Connect the load to the lowest connector on the transmitter rear panel in accordance with the tracing procedure (pos.14 **figure 12.5**). The examined route (pipeline, cable), inductive antenna or transmitting clamp can be used as a load.

To ensure safety it is strongly recommended to complete all connection works before the generation is started.

Turn on the power with external mechanical switch «I/O» on the rear panel by setting it into the «I» position pos.1. Open the cover. Turn on the power with the button **pos.2 figure 12.6.** The indicators on fields «POWER» and «PARAMETER SETUP» will start indicating.



Fig12.6



12.5 Parameter setup

The field «PARAMETER SETUP» **figure 12.7** is used for selection of one of three generation frequencies f1, f2, f3, one of three modes of sine generation (continuous «CO», one frequency transmission «PU», two frequencies transmission «2F» or charging mode «CH») and of four current loads. If necessary the "banks" of currents and frequencies can be modified quickly. The use of the transmitting antenna as a load is possible only if a generation frequency of 8192 Hz which is set automatically when the antenna is connected to the output.

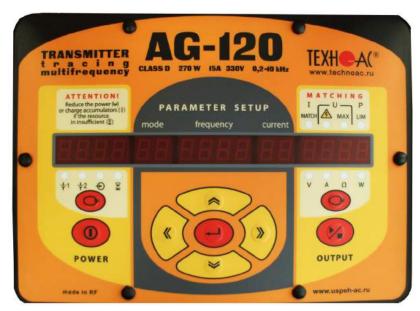


Fig12.7

1) To enter the setup mode depress the button of entering into parameters setup « --- » pos.5 while staying in the "stop" mode (no generation, yellow LEDs on the "OUTPUT" field **figure 12.7**. are not

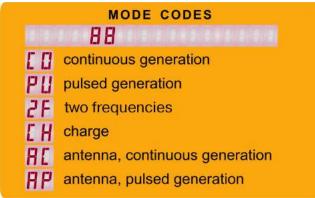


Fig. 12.8

- on). Will begin to blink field of the indicator «MODE».

 2) Depending on the task, to set the mode the buttons « » or « » » (cycle) pos.5 figure12.7 are used to select on the field "MODE" the symbol depicting the required generation mode or mode of internal accumulators charging. The mode codes are shown on figure 4.8. If the transmitting enternal in
- internal accumulators charging. The mode codes are shown on figure 4.8. If the transmitting antenna is connected to the output, the signal «AC» is indicated (mode «antenna, continuous»). The selection in this case is possible only between modes «AC» and «AP» (mode «antenna, pulsed») directly by the buttons
- 3) To set the operation frequency or current, use the button « » until the indicator «FREQUENCY» or «CURRENT» appears on the indicator screen. In the modes «CO» and «PU» the blinking value (figure) can be modified.

«♥» or«♠».

To input another value of frequency instead of the blinking one press the button «¬» so that only first digit of the figure would be blinking (the highest digit). To select another digit use the buttons «»» or « «». The blinking figure can be modified with buttons « »» or « » (0...9). To save the new value in the «bank» of frequencies (instead of the previous one), press the button «¬».

It is possible to work with the specified frequency temporarily before power is switched off, if the generation (automatic matching) is activated immediately with the button « ** » pos.10 **figure12.9.**



4) The setting of the specified current is conducted similarly to the work frequency specification. The range of specified current is 0,1...9,9 A with a step of 0,1 A. "Bank" of factory set current values has 10 following values (A): «0.1», «0.2», «0.3», «0.5», «1.0», «2.0», «3.0», «5.0», «7.0», «9,9». If necessary, the current of pulsed transmission ("PU") in the stable mode of transmission can be increased up to 15A (if there is enough power). The values of current exceeding 9,9A may not be saved in the "bank" of currents.

The high output current (up to 15 A) allows tracing of buried utility with extremely low resistance (for example, to pass the output current between grounded pipeline and grounding circuit bus). In this case the small, but



still sufficient, part of the output current is branched into the remote areas of buried utility. The serviceability is maintained till full short-circuit of the output clamps.

When selecting the load current (or power) and frequency of the transmission the following guidelines are to be followed:

- -the lower is the power the higher is power supply life
- -the lower is the current, the lower is the frequency the lower «induction» on the neighboring elements
- -the higher is the frequency the higher is sensitivity of receiver, the less current (power) is enough, energy saving is possible, recommended for high-resistance buried utilities, on the other hand, the higher level of signal penetration into the neighboring objects and, as a result of higher attenuation, the signal is spread at the less distance.
- -the higher is the current, the lower is the frequency the range of transmission and route detection is higher, but the power required is higher.

12.6 Modification of the set parameters

To modify the set parameters, stop the generation with the button « » pos.10 **figure 12.9** at the field «OUTPUT» by one or two depressions and proceed to the parameters setup. The first depression of the button « » pos.10 results in stop of the automatic matching process at the achieved level (the indicator readings are "frozen", no generation, yellow LEDs on the field «OUTPUT» are not on), second depression on the button « » results in the stop of generation (the indicator is off).

To enter the parameters modification mode depress the parameters setup button « ¬ » pos.5 while staying in the «stop» mode. The indicator field «MODE» will start blinking, to change the mode use the buttons « » or « » (by cycle) pos.5 to select the required generation mode symbol and go to modification of other parameter (frequency, current) with buttons « » or « ». The blinking value of parameters from the databank can be selected with buttons « » or « » (0...9). To modify the parameter value when the required value is not in the databank (the selected parameter blinks) depress the parameter setup button « ¬ », after that the blinking figure can be modified with buttons « » or « » (0...9). To save the new value in the data "bank" (instead of the previous one) depress the button « ¬ ».



12.7 Indication of parameters

1) Indication on the field «POWER» figure 12.10. One of the digital indicator readings is selected by

the corresponding button pos.3 by the green LEDs.

- †1- voltage on the "base" internal accumulator №1
- ±2 -voltage on the «superstructure» internal accumulator №2
 - -voltage on the external power supply input
- ∃ in the generation mode estimated power supply life meaning: «for this level of energy consumption it will work for N hours» (on base the family of discrete discharge curves for new accumulator for $t = 0^{\circ}C$). The reading «20» means «very high life time which is difficult to estimate». The reading «0,1» means: «the instrument may switch off at any moment».



Fig. 12.10

- in the «charging» mode - time of charging by the stable current (counting up) and time of charging by the stable voltage (counting down), hours/min

If two or three first LEDs are illuminated at the same time, that means that the digital field «POWER» indicates the resulting voltage, supplying the terminal power amplifier. In this the first (left) seven-segment indicator on the field «POWER» symbolically depicts the configuration of mutual connection of the power supplies. The list of possible power supply configurations and codes is given on the transmitter cover (figure 12.11).

2) Indication on the field «PARAMETER **SETUP»**

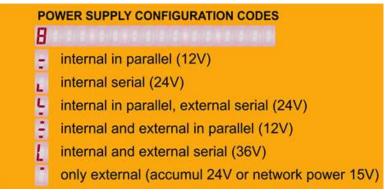


Fig. 12.11

Indication on the field «PARAMETER SETUP» is described in the sections parameters setup and parameters modifications.

3) Indication on the field «OUTPUT»

When the **power is applied** to the transmitter two situations are possible:

- If the LEDs on the field «OUTPUT» are not illuminated—the transmitter is in the standby mode («stop»). The parameter setup can be conducted or the generation (automatic matching) may be initiated immediately by depressing of the button pos. 10. The mode «stop» will last for 1 minute. If no button is depressed the internal electronic power switch will switch the power off automatically.
- If one of yellow LEDs is illuminated on the field «OUTPUT» (and the external switch pos.1 is highlighted), the power has been turned off during generation and the same mode with the previous settings is restored. The automatics tries to recover the situation through the automatic matching. If it is necessary to change the set parameters, stop the generation with the button « » pos.10 on the field «OUTPUT» («turn off» the yellow LED and illumination of the external switch with one or two pressing) and proceed to the parameters setup.

During the generation the estimated values of output parameters are indicated on the digital field «OUTPUT»: load voltage «V», load current «A», load resistance «Ω», load power «W». The accuracy of measurement (± 5 % for «V» and «A» and ± 10 % for « Ω » and «W») is sufficient for situation evaluation and decision making. The indicated parameter is selected by the button « pos.9 the LED corresponding to the selected parameter is illuminated pos.8 figure 12.10.



The power is selected automatically according to the principle: «sufficient (or maximum possible) for achieving of the specified output current (or closest possible value)». When the automatic matching is finished (or interrupted with button "START/STOP") manual control of voltage (current, power) with buttons « and « is possible. During this the indicator « always indicates the remaining life of the internal power supply (hours) depending on the accumulator discharge level and current energy consumption.

The high output voltage (above 330 V with the use of additional accumulator 12 V) and high reserve of power (up to 270 W with additional 12V accumulator) provide sufficient tracing current for long buried utilities with high resistance.

After complete attempt of automatic matching (not aborted) the field «MATCHING» pos.7 figure 12.10 reveals the result:

- «Imatch» completed successfully, specified current achieved. After generation is turned off from this condition the set parameters of generation and selected parameters of indication becomes default values, that means loaded after power interruption.
- «Umax» the voltage is not enough to achieve the specified current for this load (the load resistance is too high or the contact between output clamps with the load is broken).
 - «P lim» not enough power to achieve the specified current for this load.

The potentially «dangerous» unlimited mode of generation is depicted with a special «alert» indicator « 🚣 ». The «default» increase of the output voltage is limited by level safe for a human (24V). If necessary (for tracing the cables) it is possible to operatively remove the limitation (temporarily) if the appropriate precautions are taken.

Here the decision should be made about necessity to correct the parameters of output current. For this purpose the test tracing is recommended.

12.8 Start and stop of generation

If after power is turned on the button « pos.10 is depressed shortly in the standby mode (stop »), the generation and automatic matching – step-by-step increase of voltage at the output

until the specified current is reached shall be started. It bir is recommended to monitor bir is recommended to monitor

TRANSMITTER

CLASS D 270W 15A 330V 0,2-16 MRx

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PARAMETER SETUP

fine rower

fine rowe

utility
24.9 – supply voltage
(2 acc in series), V
CO - continue generation
1024 – frequency, Hz
4,0 – current, A

58 – power, W

is recommended to monitor the power life indicator (« » on the field «POWER»). If the output voltage («V») exceeds «24.0» the automatic matching shall stop anyway. If the specified current is not reached, the indicator "Umax" shall be on in the field «MATCHING». This is a **safe**

mode set by default when the power is on.

Fig.12.12 If higher output voltage is required to achieve the necessary current during tracing of the cables (AND APPROPRIATE SAFETY MEASURES ARE TAKEN!), the automatic matching can be started in the **«unlimited» mode**. For this purpose press the button **«**»** in the standby mode ("stop") and keep it **depressed** until the "alerting" indicator

« 🗥» is on. That means the potentially dangerous "unlimited" mode is activated, the output voltage may exceed 200 V with internal power supply and 300 V with added 12V external power supply. The «unlimited» mode shall exist until the power is off.

The current in load is selected or input from the keyboard in the indicator field «CURRENT». In the course of automatic matching the voltage on the load is increased step by step till the current in the load exceeds the value stated in the setter («CURRENT»).



In this case the voltage increase is stopped and the "Imatch" sign appears in the field «MATCHING». If the load resistance is changed in the stable mode of generation, the power selection program shall maintain the specified current within ±2dB by repeated automatic matching with appropriate adjustment of power.

The incomplete automatic matching procedure can be stopped at any point by depressing of the button « ** ». The first pressing in the course of automatic matching – «stop» of matching, second— «stop» of generation. Depression in the stable mode of generation results in «stop» of generation.

ATTENTION! ENERGY SAVING!

All manipulations with output current (power) lead to energy consumption (power supply life time) change. Observe the life time indicator « > on the filed «POWER» to make sure there is enough time to complete the tracing. To save the energy, work with the minimum sufficient power in the load. Use the mode of short-time transmission if possible. The breaks in operation help in partial replenishment of capacity. Charge the accumulators if the situation allows. Do not bring to automatic switch off through insufficient power.

Long-term storage of accumulators in discharged condition results in complete loss of their serviceability. Before long term storage charge the accumulators and recharge them at least every 6 months. The temperature during storage shall be +20...25°C.

12.9 Operation with inductive antenna

To achieve the maximum intensity of the «induction», the buried utility line and antenna frame must be located as close as possible to each other and in a single plane. Prior to connection of the frame to the output turn off the power in the "stop" mode with power button pos.2 « » figure 4.13 or with external mechanical switch. If the antenna is connected to the output when the power is on, the instrument switches to "antenna" mode characterized by permanent parameters setup. The following is indicated: mode «AC», frequency «8192», current «0,2». After transmission is activated



Inductive connection to buried utility with antenna 20 - time, h AP - pulsed generation 8192 - frequency, Hz 2.0 - current, A 29,5 - power, W

Fig. 12.13



Inductive connection to buried utility with clamp 10.5 - time, h PU - pulsed generation 512 - frequency, Hz 4.0 - current, A 20,0 - power, W

Fig. 12.14

12.10 Operation with the transmitting clamp If there are several closely located buried utilities it is recommended to

WARNING!

may heat up to 60°C

use the transmitting clamp figure 12.14 to induce the current specifically in one of them contact-free. The power consumed by the clamp is reverse proportional to the signal frequency if the voltage is constant. It is not

with the button «» pos. 10 the automatic matching results in automatic setting

with optimum specified parameters.

After that if necessary the output

voltage can be reduced or increased

with the buttons « » and « ». To continue

transmission after power interruption

During

operation of loop antenna IEM-301.3 in continuous mode, its body

long

restart with the button « » is required.

recommended to apply the power more than 60W in the continuous generation mode (CO).

It is not allowed to transmit more than 20W in continuous (CO) mode and more than 200W in pulse (PU) mode on CI-110 clamp.



12.11 Operations under precipitations

The waterproof instrument (IP54) allows operation under precipitations when the cover is closed providing the online adjustment of parameters is not required. The power is turned on/off

with external waterproof power switch «I/O» pos. 1 figure 12.15. The readings are monitored through the transparent window in the cover pos. 11 figure 12.15. Make sure the required mode is selected and start the transmission before closing the cover. Every time the power is turned on with the closed cover the system shall restart this mode (except for «AC» and «AP») with automatic matching. The transmission is indicated by highlighting of the external switch. The free connectors on the rear panel are protected by rubber plugs.



12.12 External power connection

The additional accumulator (12/24V) or power adapter output (15 V) can be connected to the upper connector of the rear panel pos.15 figure 12.15.

ATTENTION!

The external source output may have no galvanic link except for with the transmitter output. Prior to connection make sure there is no grounding, zeroing or link to the vehicle body for any of the external source outputs.

Depending on the task the instrument uses the external power for increase of the life time or increase of power or for charging.



12.13 Internal accumulators charge

Necessary instruments for charge is given on a picture:



Charger connection scheme is given on picture:



ATTENTION!!

It is advised to charge the accumulators at the ambient temperature from +20 to +25 °C



In order to start the charge of accumulators, connect the charger and transmitter as given above:

- 1. With red-black cable (AG-120.02.010) connect transmitter on EXTERNAL POWER socket on one end and to the corresponding leads ESP-240-13.5 on the other.
 - 2. Connect power supply cable of ESP-240-13.5 t o220V DC power outlet;
 - 3. Set power supply switches to "ON" and "1" positions correspondingly.
 - 4. Selecth "CH" (Charge) mode on transmitter indicator, to do that:
- - by pressing «♠» / «❤» («UP» / «DOWN») buttons, select "CH" mode on the indicator
 - 5. Press « START/STOP) button.

NOTE:

Blinking of charger indication LED (load indication) on face panel of ESP 240-13.5 indicates that charging is in process.

During charge, it is possible to see animated picture of charge stage and time estimation till fully charged accumulator «\overline{&}».

When static picture appears on the screen (not before that) charge may be stopped by pressing « START / STOP). The transmitter will be charged at least for 95%. If more time available it is recommended to continue the charge with 14.6-14.9V of stable Voltage. In 8 hours after charge start an automatic shut down will happen. Full cycle charge guarantees 100-110% of accumulator capacity.

NOTE:

Duration of "filling" stage for more than 6 hours indicates that there is "charge error". When power supply is turned on after charge error – indication in "POWER" field is blinking.



13. The joint operation of transmitter and receiver during active route detection

The inductive (active) search method is now most widespread for detection of underground buried utilities. The basis of the method is the fact that there is an electromagnetic field around the conductor with current.

The transmitter connected to one end of the monitored buried utility serves as a source of test current of special frequency. For flowing of the current it is necessary to have a special electric conductive circuit with monitored buried utility as one branch and grounding as another branch for return of current through the ground.

The maximum strength of the electromagnetic field measured above the ground surface corresponds to the axis of searched buried utility.

To properly operate the kit the following rules are to be observed:

- Transmitter grounding selection (refer to p. 12.3);
- Definition of transmitter connection type (refer to p.12.3);
- Setting of transmitter parameters (refer to p.12.5);
- Adjustment of receiver

After performing the above items you can start buried utility tracing.



Thank you for choosing Techno-AC equipment!!

- If you fave suggestions of improving the device's operation to your needs,
 - you have proposals to improve technical documentation,
- You have any questions about device operation email us to: marketing@technoac. ru or call:

+7 (496) 615-16-90

We will to solve your in no time.



Appendix 5 Specifications of AG-120

Frequency of generated signal				
Frequency of generated signal	Range 2009999			
Frequencies f1, f2, f3 (three frequencies fixed in memory), Hz	(selected in the range with a resolution of 1 Hz and accuracy of ±0,05% Hz and input in the power-independent memory)			
Frequency f4 (one «temporary»), Hz	Range 2009999 (selected instead of one of the «fixed», not input to the memory, exists while the power is on)			
Output parameters				
Output current				
Maximum in manual mode: - continuous and two frequencies generation, A - pulse generation, A	10 15			
Maximum output voltage				
 when working in safe mode, V under internal power supply, V with added external accumulator 12V, V when supplied from power adapter, V 	24 220 (170 when «2F») 330 (260 when «2F») 140 (110 when «2F»)			
Maximum output power when accumulators are f	fully charged			
- under internal power supply or from external accumulator 24V, W	120 continuous at a load of 1,2300 Ohm / 180 pulsed at a load of 0,8200 Ohm			
- with added external accumulator 12V, W	180 continuous at a load of 1,8450 Ohm / 270 pulsed at a load of 1,2300 Ohm			
- from power adapter, W	70 at a load of 0,7200 Ohm			
NOTE. When incompletely charged or (and) frequencies above the "logarithmic middle point" of the range (1,4kHz) the reduction of the maximum power with an increase of frequency and load resistance is possible at no more than 3dB.				
Resistance range for matched loads, broader that	an I			
For minimum specified current (0,1A) - for internal power, Ohm -with external accumulator 12V added, Ohm	42200 (41700 when «2F») 43300 (42600 when «2F»)			
For maximum continuous current (10A) - for internal power, Ohm -with external accumulator 12V added, Ohm	01,2 01,8			
For maximum pulsed current (15A) - for internal power, Ohm -with external accumulator 12V added, Ohm	00,8 01,2			
Matching with the load				
	- automatic, providing achieving of the specified current in the load - manual (buttons « » or « »)			

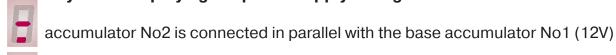


Design parameters		
Output power amplifier	Pulsed, technology CLASS D(BD), Efficiency factor > 80%	
LED-based superbright digital indicators of high temperature range	- all supply voltages - modes and settings - power resource - «OUTPUT MULTIMETER»: «output voltage», «current in load», «load resistance», «power in load»	
Control	Nine-button keyboard and external power switch with generation indicator providing work under rain with closed cover (due to parameter setup "memorizing"). Intuitive interface	
Dimensions of electronic block (case), maximum, mm	305x270x194	
Weight of electronic block, maximum, kg	12	
Operating temperature range, °C	-30+50	



Appendix 6

Symbols displaying the power supply configuration of the AG-120 transmitter



accumulator No2 is connected in series with the base accumulator No1 (24V)

the external accumulator (12V) is connected in series to the internal accumulators No1 and No2 connected in parallel (24V).

the external accumulator (12V) is connected in parallel to the internal accumulators No1 and No2 connected in parallel (24V).

the external accumulator (12V) is connected in series to the internal accumulators No1 and No2 connected in series (36V)

the power amplifier is supplied only from external source with an elevated voltage (external accumulator 24B or power adapter 15V). The internal (accumulators No1 and No2) supply the rest of the circuit.

The horizontal segments designate the power supplies with «-» output connected to the common wire of the circuit. The base internal accumulator No1 is always connected to the common ground and is designated by the lowest horizontal segment (if participates in the power amplifier supply). The vertical segments designate the power supplies with «-» output connected to the «+» of the other sources («superstructure sources»).

External supply	Power source connection configuration			
type	External only	All in parallel	External in series with mutually parallel internal ones	All in series
Accumulator 12 V / ≥24 Ah	-	Increase depends from external accumulator capacity	Life time x2	Either life time or Pmax x1,5
Accumulator 24 V / 15 A	The life time is fully defined by the external accumulator capacity			
Power adapter 15 V / 15 A	The life time is fully defined by 220 V AC mains availability.		_	

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Symbolic depiction of the AG-120 multifrequency transmitter operation modes

E 0 PU 2F E H RE

continuous generation

pulsed generation (short transmissions)

two frequencies (frequencies sent in turn)

charging of internal accumulators

transmitting antenna connected, continuous generation

transmitting antenna connected, pulsed generation

Indication of emergency situations during the AG-120 multifrequency transmitter operation

Indication	Reason	Implication	
Er 10	Signal reached minimum	Incorrect actions of the operators when	
Er 11	Signal reached maximum	the level of output signal is changed manually with the buttons « » or « ». The	
Er 12	Power reached maximum		
Er 14	Current in load reached maximum	transmission is not stopped	
Er 20	Encountered external power voltage not allowed for charging		
Er 21	External power voltage during generation has been too low		
Er 22	Voltage of one of internal accumulators has been too low		
Er 23	Voltage of external power has been too high	Indication of emergency situations resulting in automatic switching the	
Er 30	Current mode did not match to "presence/absence" of transmitting antenna due to incorrect connection	transmission off	
Er 40	Highest allowed current in output cascade has been exceeded		
Er 41	Highest allowed consumption current has been exceeded		